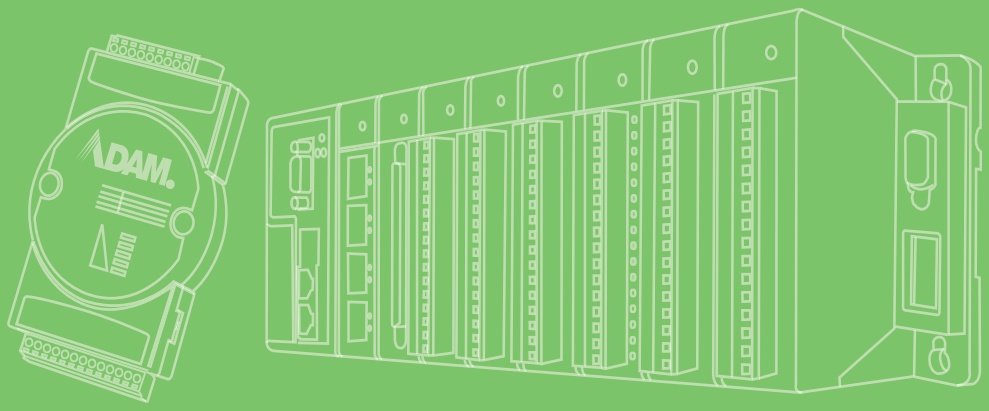

User Manual

AMAX-5070

Modbus/TCP Communication Coupler

ADVANTECH

Enabling an Intelligent Planet

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Advantech warrants to you, the original purchaser, that each of its products will be free from defects in materials and workmanship for two years from the date of purchase.

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Because of Advantech's high quality-control standards and rigorous testing, most of our customers never need to use our repair service. If an Advantech product is defective, it will be repaired or replaced at no charge during the warranty period. For out-of-warranty repairs, you will be billed according to the cost of replacement materials, service time and freight. Please consult your dealer for more details.

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1. Collect all the information about the problem encountered. (For example, CPU speed, Advantech products used, other hardware and software used, etc.) Note anything abnormal and list any onscreen messages you get when the problem occurs.
2. Call your dealer and describe the problem. Please have your manual, product, and any helpful information readily available.
3. If your product is diagnosed as defective, obtain an RMA (return merchandize authorization) number from your dealer. This allows us to process your return more quickly.
4. Carefully pack the defective product, a fully-completed Repair and Replacement Order Card and a photocopy proof of purchase date (such as your sales receipt) in a shippable container. A product returned without proof of the purchase date is not eligible for warranty service.
5. Write the RMA number visibly on the outside of the package and ship it prepaid to your dealer.

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Declaration of Conformity

CE

This product has passed the CE test for environmental specifications when shielded cables are used for external wiring. We recommend the use of shielded cables. This kind of cable is available from Advantech. Please contact your local supplier for ordering information.

Test conditions for passing also include the equipment being operated within an industrial enclosure. In order to protect the product from damage caused by electrostatic discharge (ESD) and EMI leakage, we strongly recommend the use of CE-compliant industrial enclosure products.

FCC Class A

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference. In this event, users are required to correct the interference at their own expense.

Technical Support and Assistance

1. Visit the Advantech website at www.advantech.com/support to obtain the latest product information.
2. Contact your distributor, sales representative, or Advantech's customer service center for technical support if you need additional assistance. Please have the following information ready before you call:
   - Product name and serial number
   - Description of your peripheral attachments
   - Description of your software (operating system, version, application software, etc.)
   - A complete description of the problem
   - The exact wording of any error messages

Safety Precaution - Static Electricity

Follow these simple precautions to protect yourself from harm and the products from damage.

- To avoid electrical shock, always disconnect the power from your PC chassis before you work on it. Don't touch any components on the CPU card or other cards while the PC is on.
- Disconnect power before making any configuration changes. The sudden rush of power as you connect a jumper or install a card may damage sensitive electronic components.

Safety Instructions

1. Install the system only in area with restricted access.
2. Read these safety instructions carefully.
3. Retain this user manual for future reference.
4. Disconnect the equipment from all power outlets before cleaning. Use only a damp cloth for cleaning. Do not use liquid or spray detergents.
5. For pluggable equipment, the power outlet socket must be located near the equipment and easily accessible.
6. Protect the equipment from humidity.
7. Place the equipment on a reliable surface during installation. Dropping or letting the equipment fall may cause damage.
8. The openings on the enclosure are for air convection. Protect the equipment from overheating. Do not cover the openings.
9. Ensure that the voltage of the power source is correct before connecting the equipment to a power outlet.
10. Position the power cord away from high-traffic areas. Do not place anything over the power cord.
11. All cautions and warnings on the equipment should be noted.
12. If the equipment is not used for a long time, disconnect it from the power source to avoid damage from transient overvoltage.
13. Never pour any liquid into an opening. This may cause fire or electrical shock.
14. Never open the equipment. For safety reasons, the equipment should be opened only by qualified service personnel.
15. If any of the following occurs, have the equipment checked by service personnel:
    - The power cord or plug is damaged.
    - Liquid has penetrated the equipment.
    - The equipment has been exposed to moisture.
    - The equipment is malfunctioning, or does not operate according to the user manual.
    - The equipment has been dropped and damaged.
    - The equipment shows obvious signs of breakage.
16. Do not leave the equipment in an environment with a storage temperature of below -20 °C (-4 °F) or above 60 °C (140 °F) as this may damage the components. The equipment should be kept in a controlled environment.
17. CAUTION: Batteries are at risk of exploding if incorrectly replaced. Replace only with the same or equivalent type as recommended by the manufacturer. Discard used batteries according to the manufacturer's instructions.
18. In accordance with IEC 704-1:1982 specifications, the sound pressure level at the operator's position does not exceed 70 dB (A).

DISCLAIMER: These instructions are provided according to IEC 704-1 standards. Advantech disclaims all responsibility for the accuracy of any statements contained herein.

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Chapter 4 Coupler and SubDevice Configuration

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Chapter 1

Introduction

1.1 Introduction

In order to enhance the experience of AMAX-5070, please download the below manual and software from Advantech office website:

AMAX-5000 Series I/O Modules User Manual

Advantech I/O Module Utility

This manual will only introduce AMAX-5070 Modbus/TCP Coupler. To know more about the AMAX-5000 series I/O modules, please download AMAX-5000 Series I/O user manual from our official website.

1.2 Hardware System Diagram

For the example demonstration showing how to use AMAX-5070, the system hardware architecture can be shown as Figure 1.1. LAN port 1 and 2 can be connected by MainDevice(MDevice) via Modbus/TCP but also LAN port 2 provide cable redundancy via EtherCAT. The cable redundancy system diagram in tree topology please refer to the Figure 1.2 and the ring topology refer to the Figure 1.3.

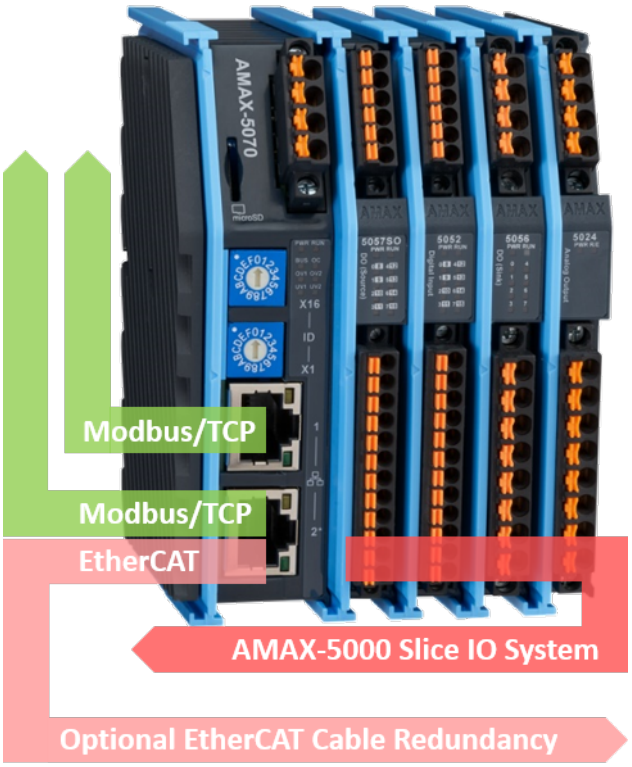

Figure 1.1 AMAX-5070 Hardware System Diagram

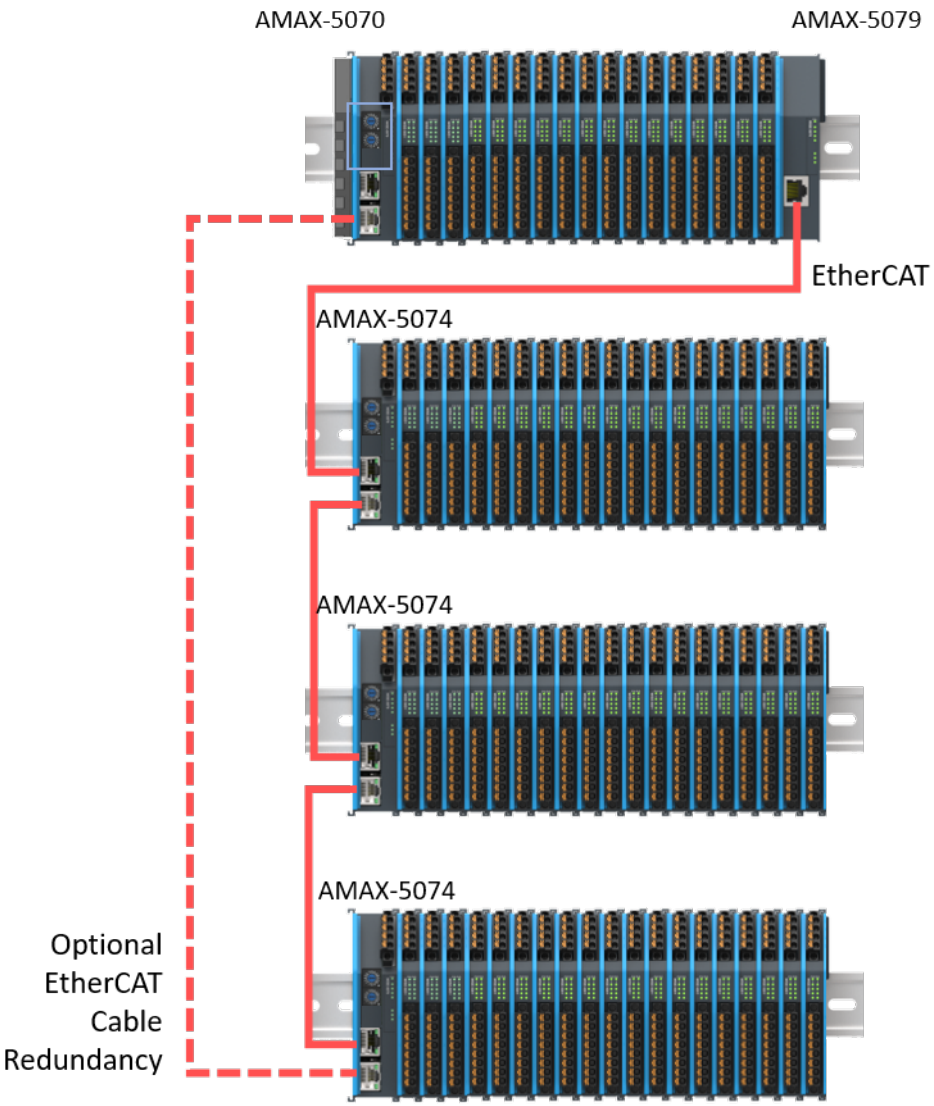

Figure 1.2 AMAX-5070 Cable Redundancy Hardware System Diagram in Tree Topology

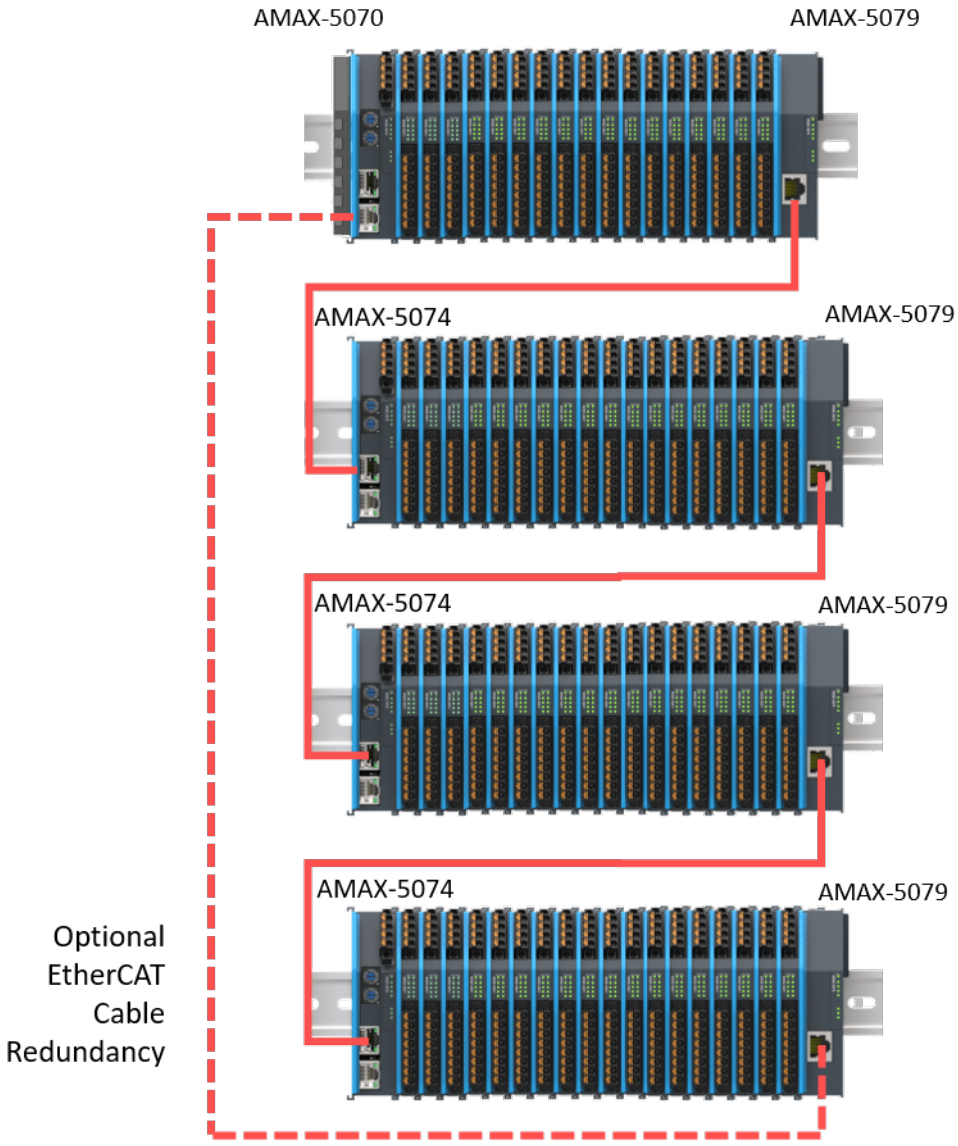

Figure 1.3 AMAX-5070 Cable Redundancy Hardware System Diagram in Ring Topology

1.2.1 Power Application and Consumption

The AMAX-5070 provide maximum 2A current for the following SubDevices. Inserting AMAX-5001 between I/O modules if user demand to apply more SubDevices (Figure 1.4). For the power modules and SubDevices power consumption please refer to the Table 1.1 and Table 1.2.

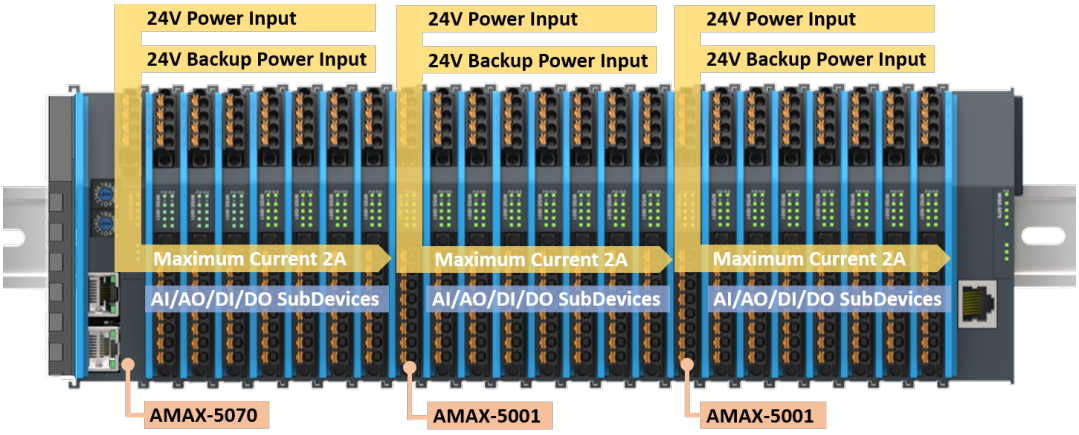

Figure 1.4 Power Module Application Diagram

Table 1.1: Coupler and Power Module Rated Voltage and Mac Current		
Module Name	**Rated Voltage (VDC)**	**Maximum Current (A)**
AMAX-5001	24 (±20%)	2
AMAX-5070	24 (±20%)	2
AMAX-5074	24 (±20%)	2

Table 1.2: SubDevice Power Consumption	
Module Name	**Power Consumption (W)**
AMAX-5079	N/A
Other AMAX-5000 Series SubDevices	Approx. 3[1]

[1]: For each module's precious power consumption, please refer to the **AMAX-5000 Series I/O User Manual**.

1.2.2 Hardware Installation and information

For the AMAX-5070 and AMAX-5000 Series I/O modules' Hardware permissible installation positions, Wiring, Cable Length, Cable Selection, RJ45 Selection, and Electromagnetic Protection. Please refer to the **AMAX-5000 Series User Manual.**

1.2.3 AMAX-5070 Support SubDevices List

The supporting SubDevices for AMAX-5070, please download Advantech I/O Module Utility from AMAX-5070 website and following this chapter **Subordinate Node Information page (SubDevice)**.

Chapter 2

AMAX-5070 Modbus/ TCP Coupler with ID Switch

2.1 AMAX-5070 Specification

AMAX-5070 is a coupler for AMAX-5000 slice IO system. It is a compact and flexible Modbus/TCP IO System. AMAX-5000 series IO modules have some common design features to help customers shorter their engineering time. This includes push-in wiring terminal / front LED for diagnosis / slide-in installation on DIN rail as well as a bus power monitoring mechanism.

Figure 2.1 AMAX-5070 Module

2.1.1 General

- **Certification:** CE, FCC class A
- **Connector:** Pluggable 4P push-in terminal (#24~16 AWG) and 2x RJ45
- **Module Enclosure:** Polycarbonate + Aluminum Alloy
- **Protocol:** Modbus TCP
- **Transmission Rate:** 100Mbps
- **LED Indicator:** PWR, RUN, Power Diagnosis LED
- **Weight:** Approx. 190g

2.1.2 Power Input

- **Rated Voltage:** 24VDC (±20%)
- **Dual Power Input:** Supported
- **Max Current on Bus:** 2A
- **Diagnosis Function:**
  - Over/under voltage for input 1&2
  - Over current output on bus

2.1.3 Modbus/TCP Coupler

- **Function:** Coupling AMAX-5000 EtherCAT IO Module to Modbus/TCP network
- **Cable:** Ethernet/EtherCAT cable (min. Cat. 5), shielded
- **Distance between stations:** Max. 100 m (100BASE-TX)
- **Interface:** 2 x RJ45,
  - LAN1: Modbus/TCP,
  - LAN2: Modbus/TCP (default) or EtherCAT Cable Redundancy
- **TCP Connection No.:** 16
- **Response Time:** 5ms
- **IO Configuration:** Advantech I/O Module Utility
- **Maximum IO Modules:** 256 (excluding AMAX-5079)
- **Group ID Support:** 0~255 (maximum 20 groups)

2.1.4 Environment

- **Operation Temperature:** -25~60°C (vertical mounted)
- **Storage Temperature:** -40~85°C
- **Relative Humidity:** 95% (non-condensing)
- **Storage Humidity:** 95% (non-condensing)

2.1.5 Reliability Test

- **High Temperature Test:** IEC 68-2-78
- **Low Temperature Test:** IEC 68-2-2
- **Random Vibration Test:** IEC 68-2-64
- **Shock Test:** IEC 68-2-27
- **Package Drop Test:** Federal Standard

2.2 LED Indicator

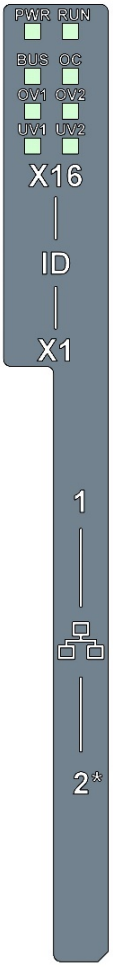

Figure 2.2 AMAX-5070 Module LED Indicator

Table 2.1: AMAX-5070 Module LED Indicator

LED	Color	Indication	Behavior
PWR	Green	On	Power On
	Orange	On	Locating Module
RUN	Green	On	EtherCAT Connected
		Blinking	EtherCAT Connecting
BUS	Green	On	Bus Power On
OC	RED	On	Bus Over Current (2A)
OV1	RED	On	V1 Over-voltage (28.8V)
OV2	RED	On	V2 Over-voltage (28.8V)
UV1	RED	On	V1 Under-voltage (19.2V)
UV2	RED	On	V2 Under-voltage (19.2V)

2.3 ID Switch

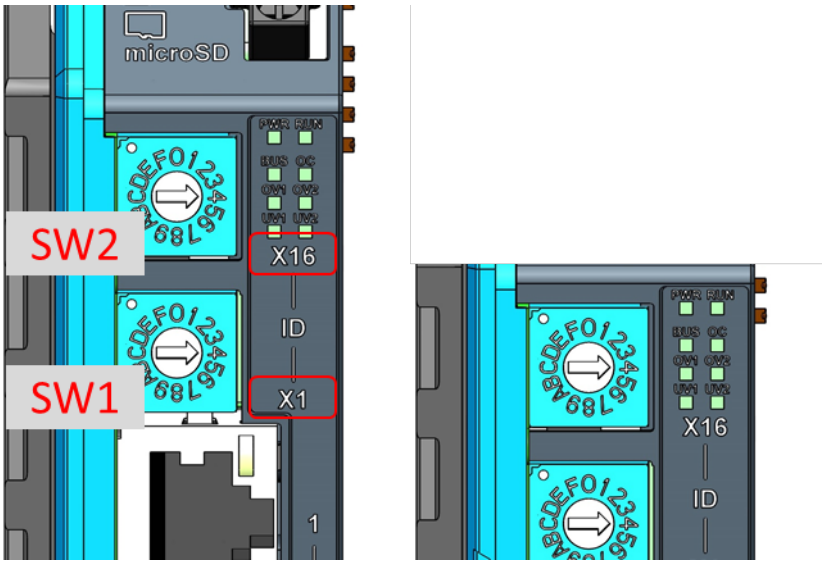

Figure 2.3 AMAX-5070 ID Switch

Table 2.2: AMAX-5070 ID Switch

Switch Number (Top to Bottom)	Multiple	Range (HEX)
SW2	x16	0 ~ F
SW1	x1	0 ~ F
Example	(SW2, SW1) = (4, C), then ID = 4x16 + 12x1 = 76	

2.4 Pin Definition

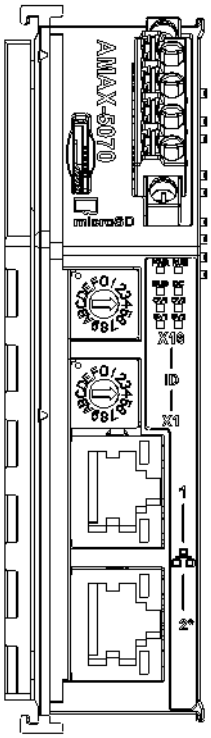

Figure 2.4 AMAX-5070 Module Front View

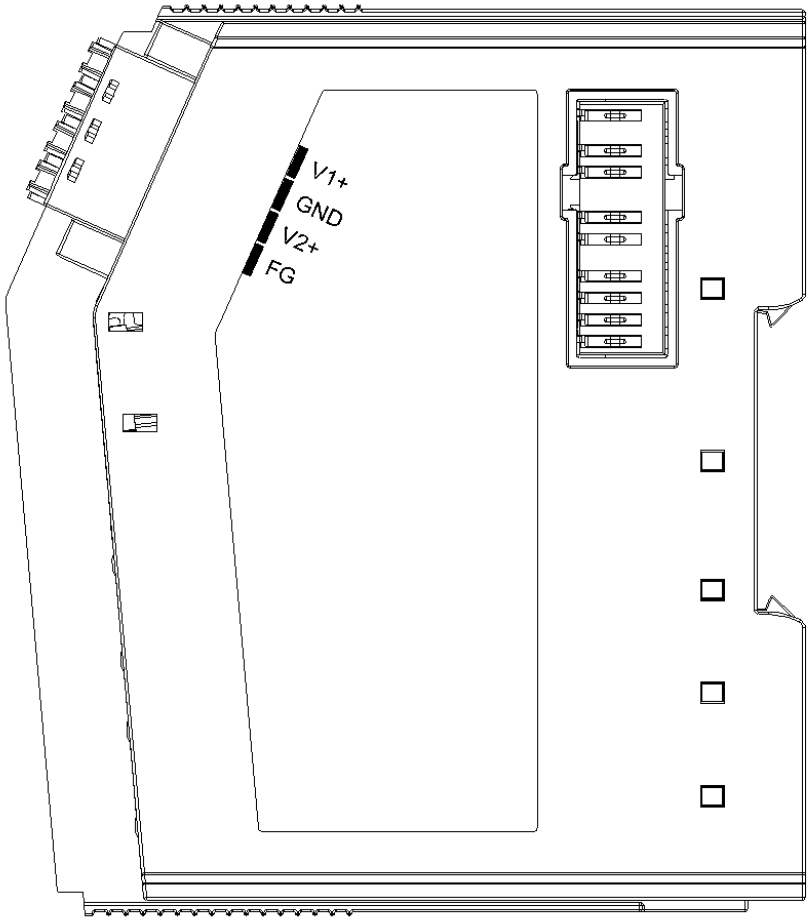

Figure 2.5 AMAX-5070 Module Side View

Table 2.3: Upper 4-Pin Connector	
Pin Number (Top to Bottom)	**Pin Definition**
1	V1+
2	GND
3	V2+
4	FG

Table 2.4: Lower 2 LAN Port	
LAN Number (Top to Bottom)	**Port Definition**
1	Modbus/TCP signal input
2	Modbus/TCP signal input or EtherCAT cable redundancy

2.5 Application Wiring

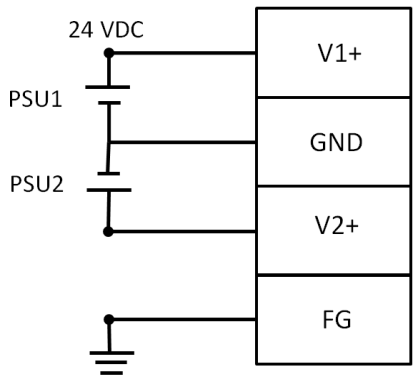

Figure 2.6 Wiring for AMAX-5070 Power Input

2.6 Dimensions

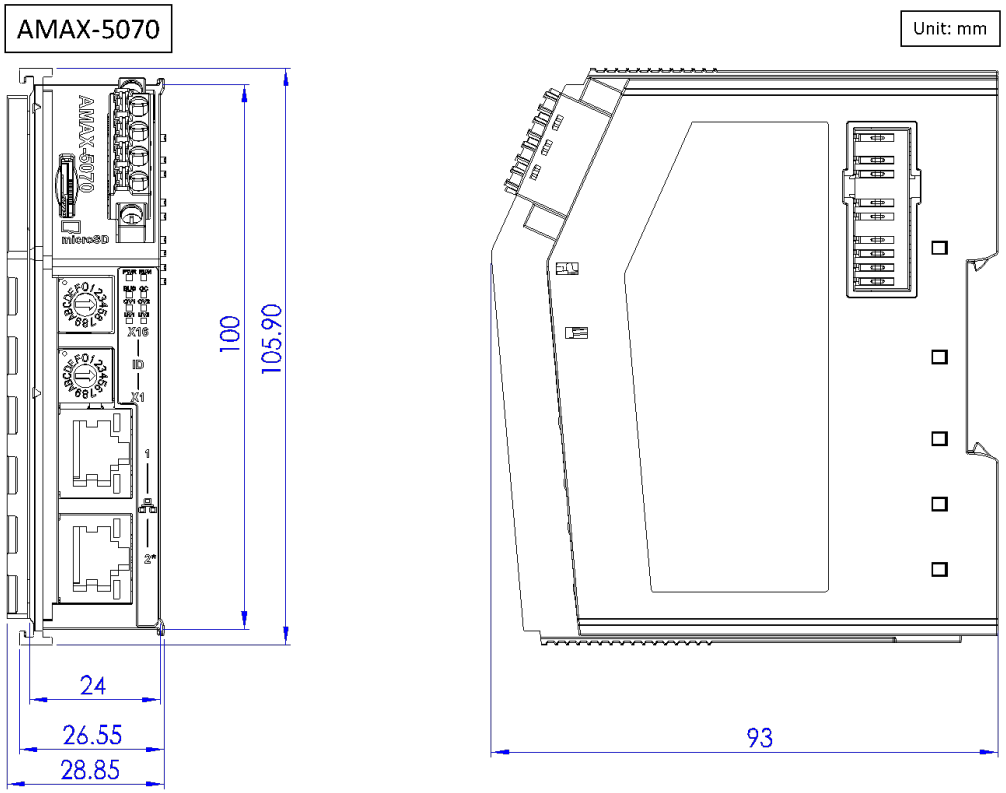

Figure 2.7 AMAX-5070 Dimensions

2.7 AMAX-5070 Object Dictionary

Table 2.5: Input Data (4x9901 - 4x9913)

Index (hex)	Name	Meaning	Data type	Flags	Default value
4x9901	Over_Voltage_1	Voltage 1 > 28.8V (24V*1.2) [1]	UINT	RO	0x0000
4x9902	Under_Voltage_1	Voltage 1 < 19.2V (24V*0.8) [1]	UINT	RO	0x0000
4x9903	Over_Voltage_2	Voltage 2 > 28.8V (24V*1.2) [1]	UINT	RO	0x0000
4x9904	Under_Voltage_2	Voltage 2 < 19.2V (24V*0.8) [1]	UINT	RO	0x0000
4x9905	Over_Current	Bus current > 2A [1]	UINT	RO	0x0000
4x9906	Voltage_1	Input voltage 1	UINT	RO	0x0000
4x9907	Voltage_2	Input voltage 2	UINT	RO	0x0000
4x9908	Current	Input current	UINT	RO	0x0000
4x9909	ID Switch	Rotary switch value	UINT	RO	0x0000
4x9910	Module_count	Current SubDevice Quantity (Reserved)	UINT	RO	0x0000
4x9911	Module_count	Current SubDevice Quantity [2]	UINT	RO	0x0000

Table 2.5: Input Data (4x9901 - 4x9913)					
4x9912	Cable_redundancy_status	Cable redundancy status	UINT	RO	0x0000
4x9913	Cable_redundancy_linking	Cable redundancy linking status	UINT	RO	0x0000

[1]: The formula to calculate the real voltage or current is as follows: Real Voltage/ Current = (Measured voltage / 1000). For example, if the measured voltage is 24168, the real voltage would be 24.168 V.

[2]: This value won't count the AMAX-5070 and AMAX-5079.

Chapter 3

System Configuration

3.1 Connect and Search Modules

3.1.1 Searching for the Coupler

Right click Ethernet and select the Search Device (Figure 3.1). The default node name is AMAX-5070, which is the main node of the device.

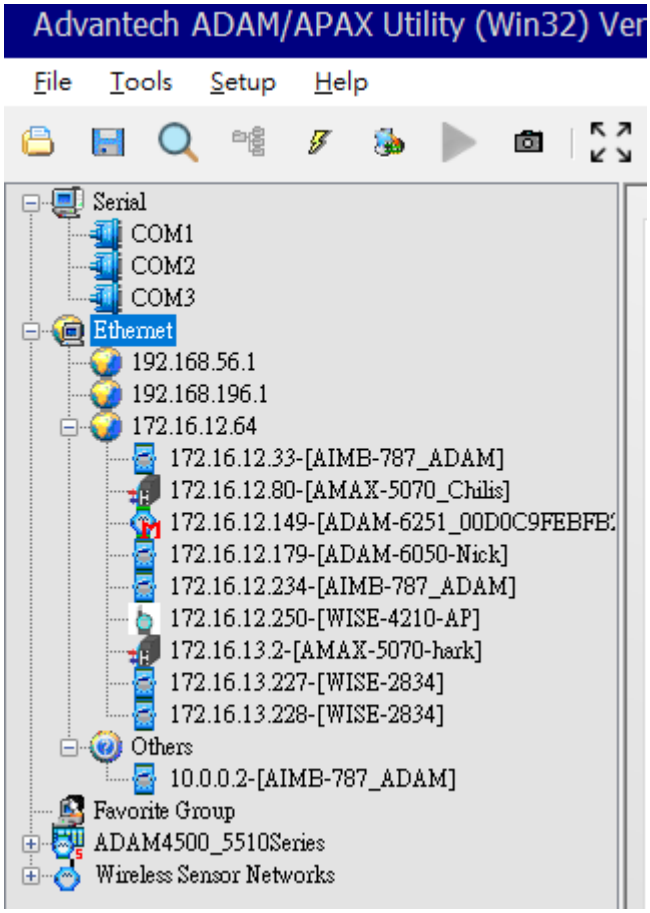

Figure 3.1 Searching for AMAX-5070

If Coupler (e.g. AMAX-5070, AMAX-5074) is under a different network segment, it will be displayed under the Others node (Figure 3.2).

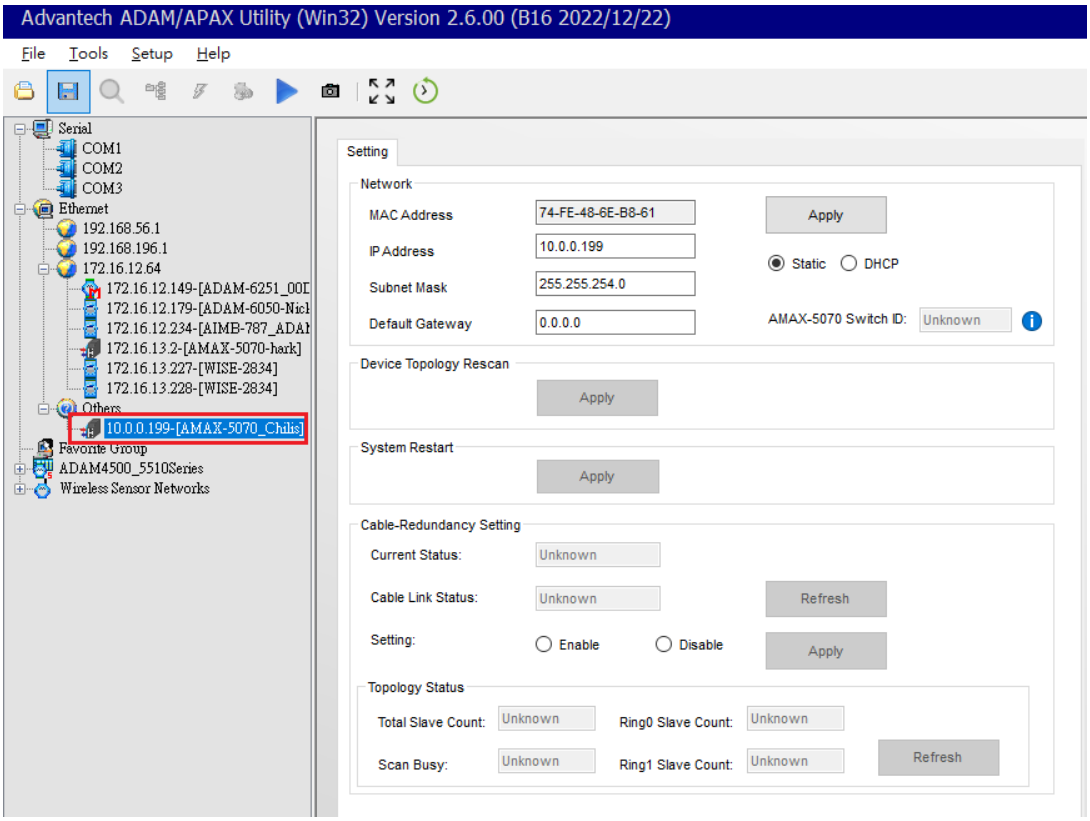

Figure 3.2 : AMAX-5070 in Different Network

3.1.2 Searching for the EtherCAT SubDevice

Clicking on the Coupler will display the current conditions and topology of the SubDevices. In the first layer, you will find the AMAX-5070 and AMAX-5074 device. In the second layer, you will find SubDevices such as AMAX-5024 and AMAX-5051. These SubDevices are positioned under either AMAX-5074 or AMAX-5070 (as shown in Figure 3.3). This hierarchical arrangement allows for a clear representation of the connectivity and placement of the SubDevices within the system.

The label "G0" after the Coupler name signifies Group 0. This number, representing the Group ID, will be automatically synchronized according to the rotary switch on the Coupler. For instance, if the rotary switch on an AMAX-5074 Coupler is set to (x16, x1)=(A,1), the Group ID will be set to G161.

However, in the case of AMAX-5070, the Group ID is always set to G0 (Group ID 0) and is not affected by the rotary switch on the Coupler. The Group ID for AMAX-5070 remains fixed and does not change based on the rotary switch position.

The label "S0" after the SubDevice name indicates that it is the first module connected in the whole system. In Figure 3.3, the first module is AMAX-5056, which has been assigned the label S0. The second module, which is an AMAX-5018, has been assigned the label S1. The third module, AMAX-5018, has been assigned the label S2.

If a module is not currently supported or recognized, it will be marked as Unknown. This typically occurs when the module is not compatible with the system or when its information is not available or updated in the current configuration.

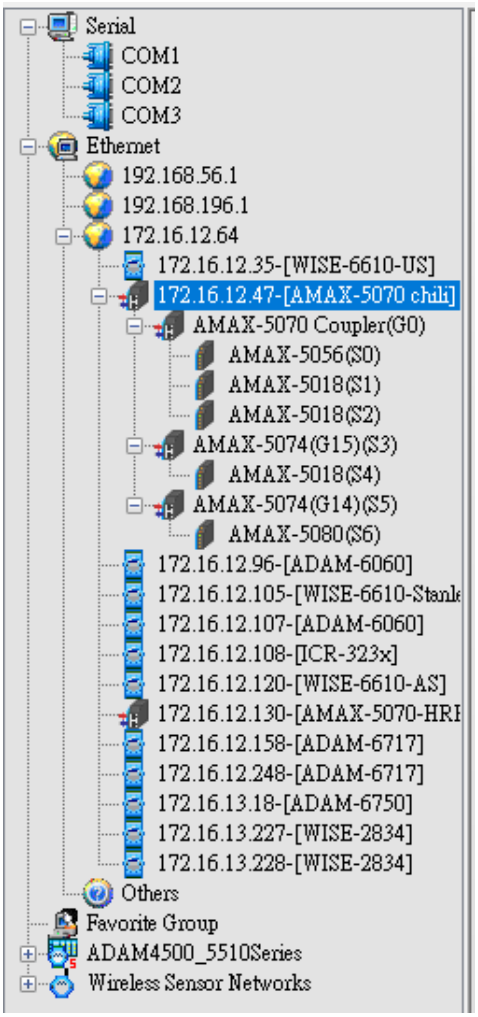

Figure 3.3 : The Subdevice Condition and Topology

The node will display an red exclamation mark "!" when there is a conflict with the Group ID.

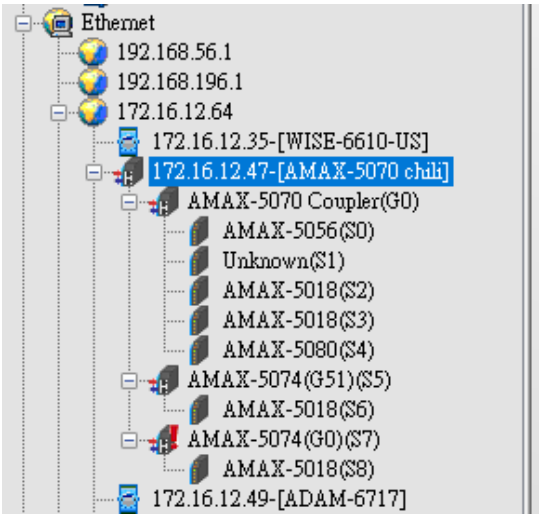

Figure 3.4 Group ID Conflict

3.2 Module Information

Clicking on the main node will display the information and configuration (Figure 3.5). If the following error message pops up, it indicates that the utility has recognized the same network segment but the command cannot reach the module due to subnet mask settings (Figure 3.6).

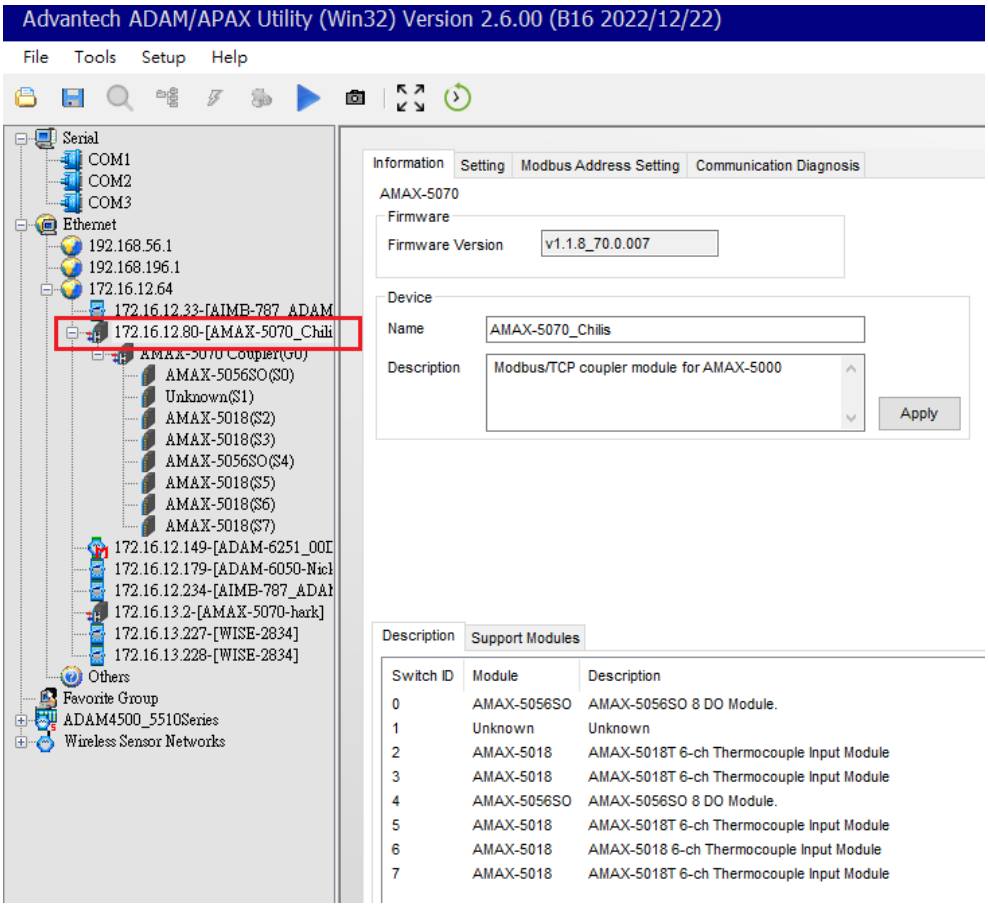

Figure 3.5 Coupler Configuration Page

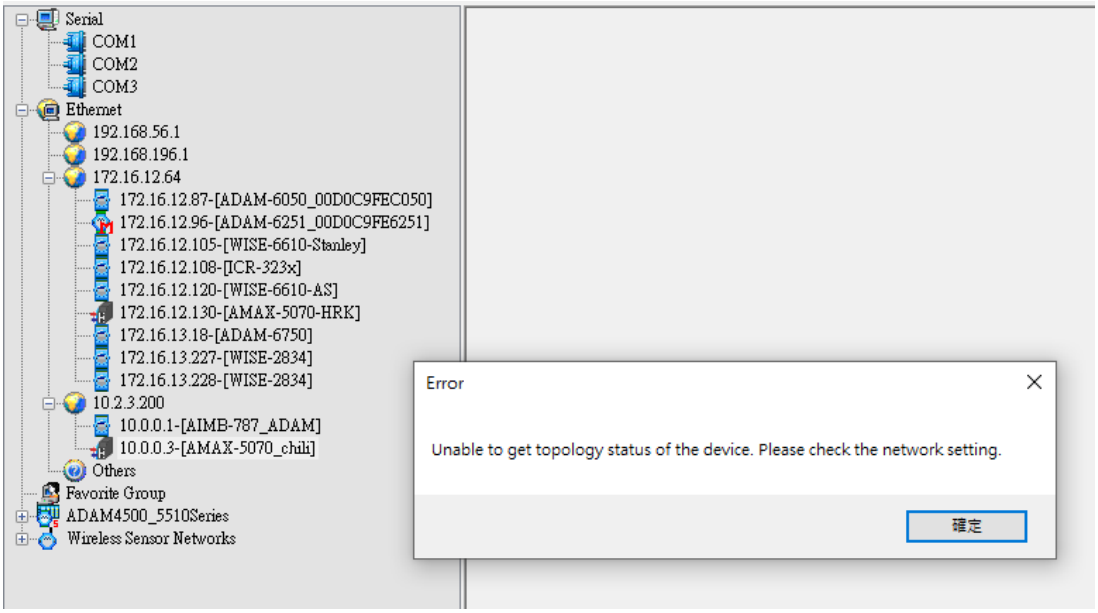

Figure 3.6 Different Subnet Mask Error

E.g.

If the Host IP is 10.2.3.200 with a subnet mask of 255.255.255.0, and the AMAX-5070's IP is 10.0.0.3 with a subnet mask of 255.0.0.0.

Both IP addresses have the first octet as 10, which leads the Utility to identify them as the same network segment.

However, due to the subnet mask configuration, the host and AMAX-5070 belong to different network segments (the host's network portion is 10.2.3.0, and AMAX-5070's network portion is 10.0.0.0), resulting in communication failure.

At this point, a page will appear allowing the user to reconfigure the IP address of AMAX-5070.(Figure 3.7)

If you do not want to change the IP addresses of both the Host and AMAX-5070, another approach is to modify the subnet mask of both devices to 255.0.0.0. By doing so, both devices will be within the same network (10.0.0.0), enabling proper communication between them.

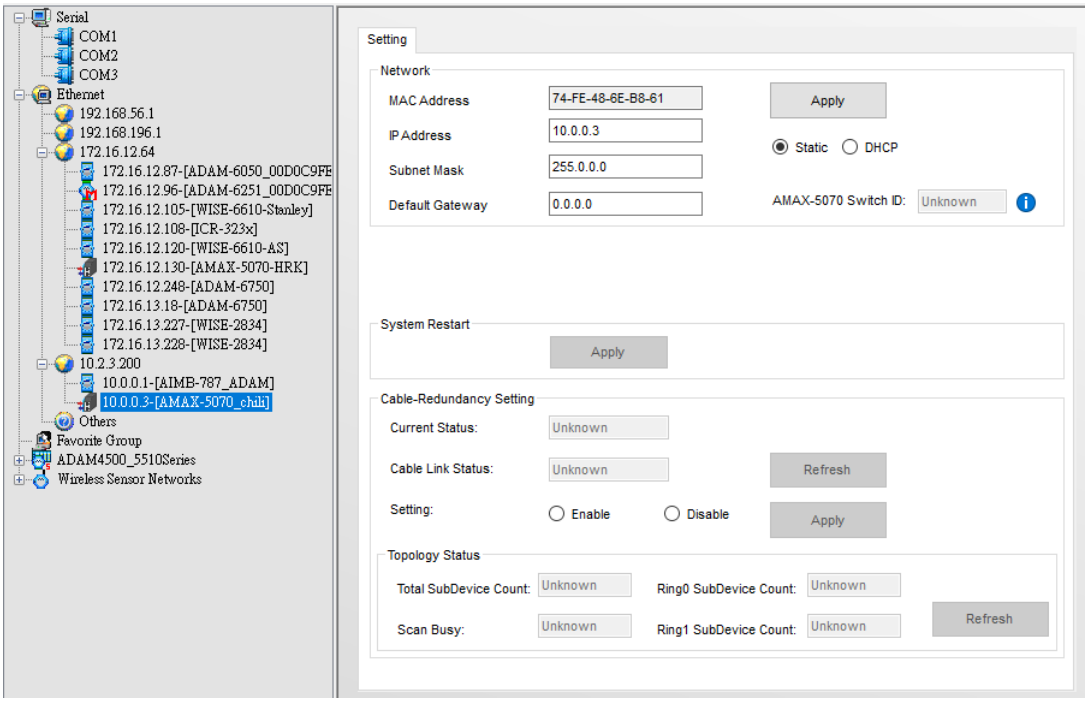

Figure 3.7 Re-setting the AMAX-5070 IP Address

For different network, the AMAX-5070 Coupler will display the Setting page if the module was in the different Internet segment.

In this condition, the user only can adjust the Internet configurations (e.g. IP address), the other option would be display Unknown, meaning it can't be adjusted. (Figure 3.8)

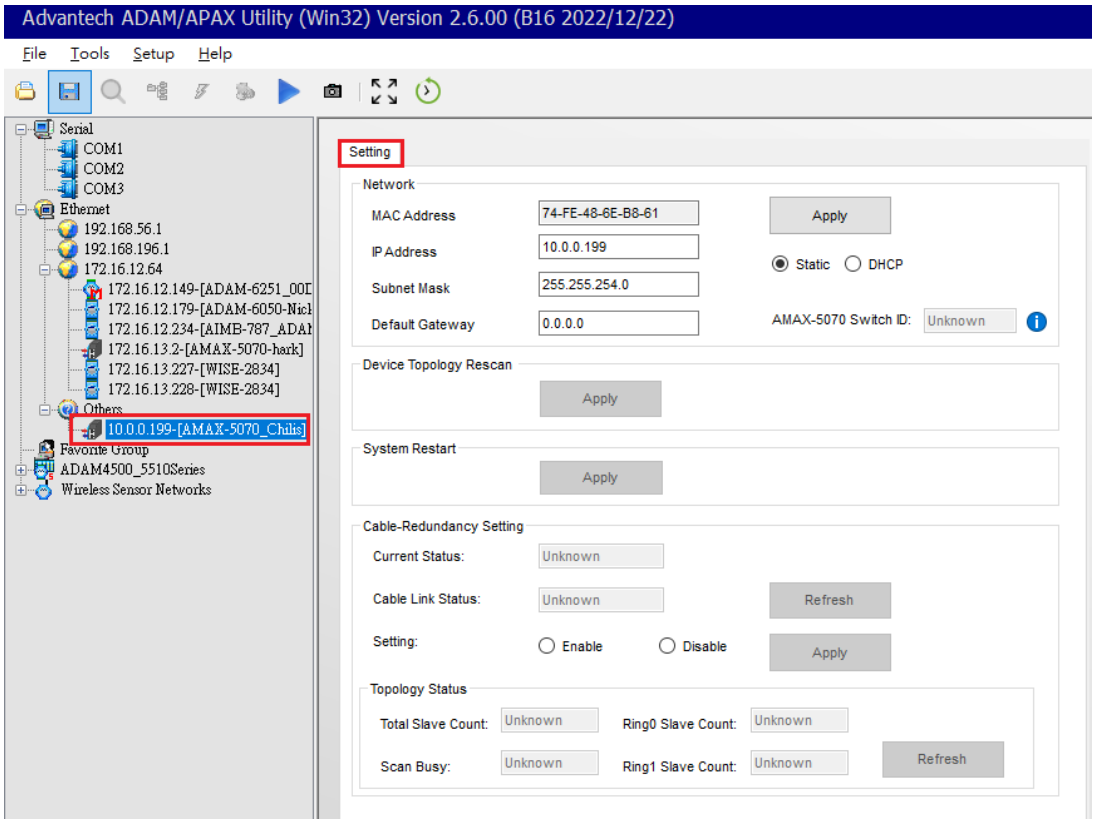

Figure 3.8 Coupler Configuration in Different Internet Segment

3.2.1 Main Node Information page (Coupler)

In the page Information will display Firmware Version and user can modify the Device Name and Description. (Figure 3.9)

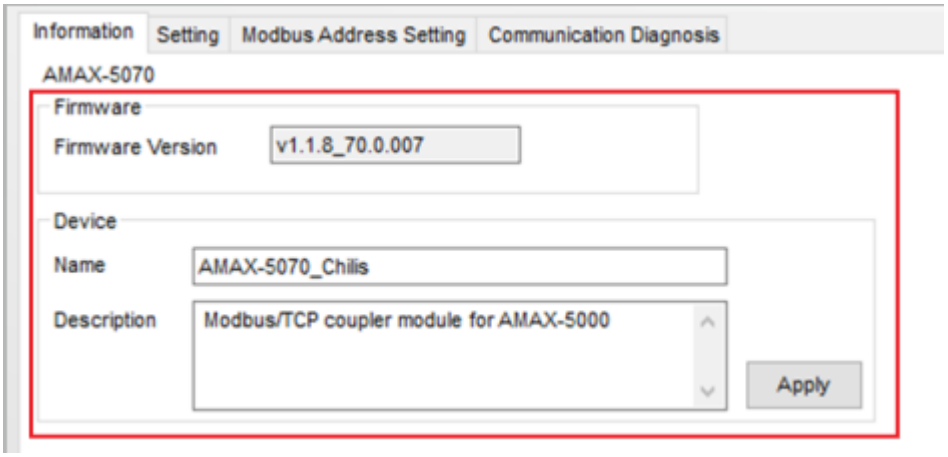

Figure 3.9 Coupler Information Page

3.2.2 Subordinate Node Information page (SubDevice)

The SubDevice node of Information will display Module, Current Connected Module and Description. (Figure 3.10)

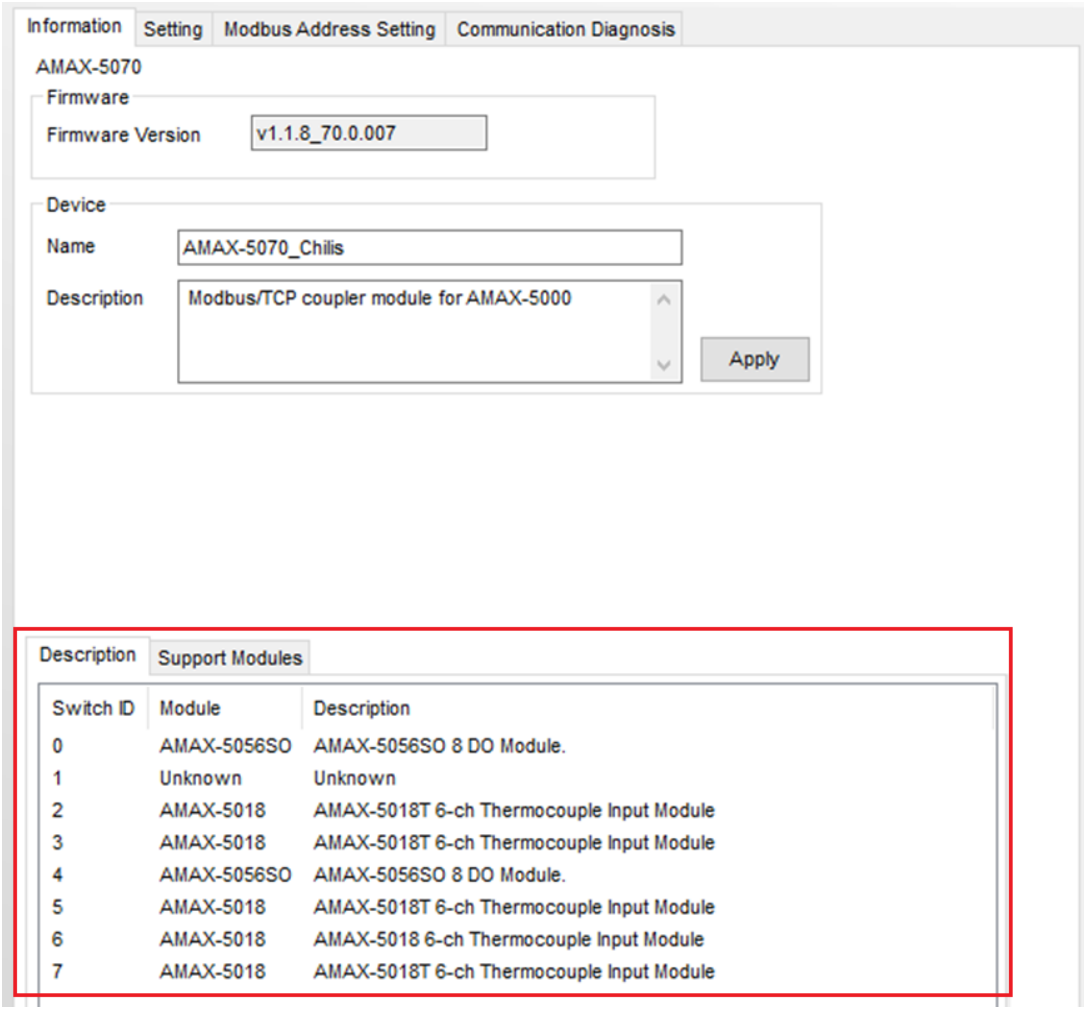

Figure 3.10 SubDevice Information Page

3.2.3 SubDevice Support List

Click the Support Modules tab and check the supported SubDevices list (Figure 3.11).

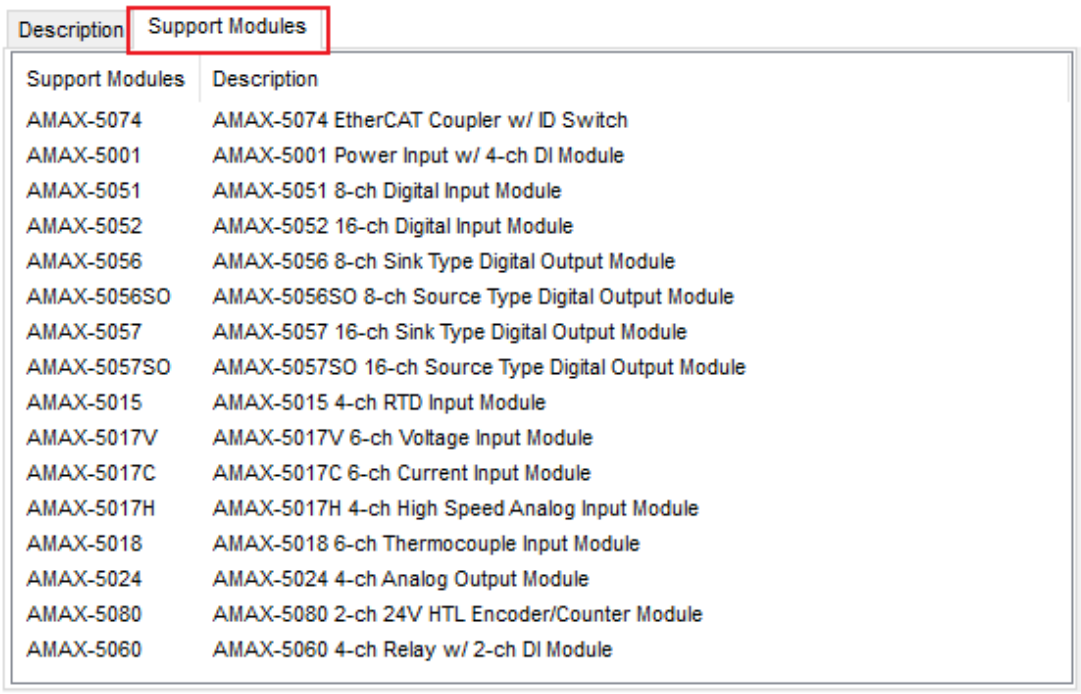

Figure 3.11 Support SubDevice List

3.3 Module Setting

3.3.1 Network Configuration

DHCP and Static Mode can be selected dependence on different applications. DHCP will be assigned internet configuration from DHCP server; In Static Mode user can modify IP address, Subnet Mask and Default Gateway. (Figure 3.12)

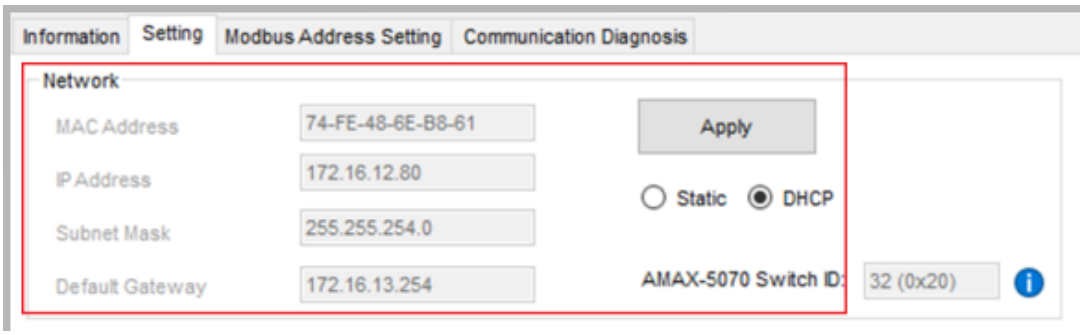

Figure 3.12 Network Configuration Page

3.3.2 AMAX-5070 Switch ID

AMAX-5070 rotary switch state would be displayed in the Setting page (Figure 3.13). For more information about switch ID function please check the blue information icon nearby the switch ID number.

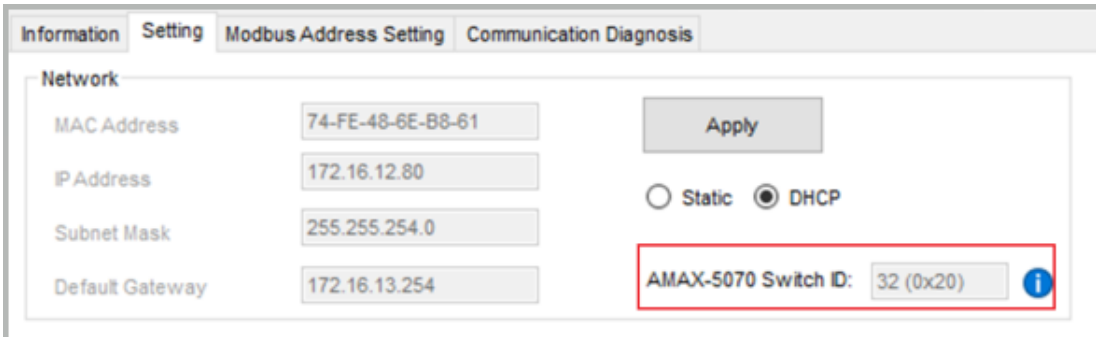

Figure 3.13 AMAX-5070 Switch ID

3.3.3 Rescan the SubDevice and Topology

User can rescan the SubDevice and Topology in Device Topology Rescan then click the Apply button. (Figure 3.14)

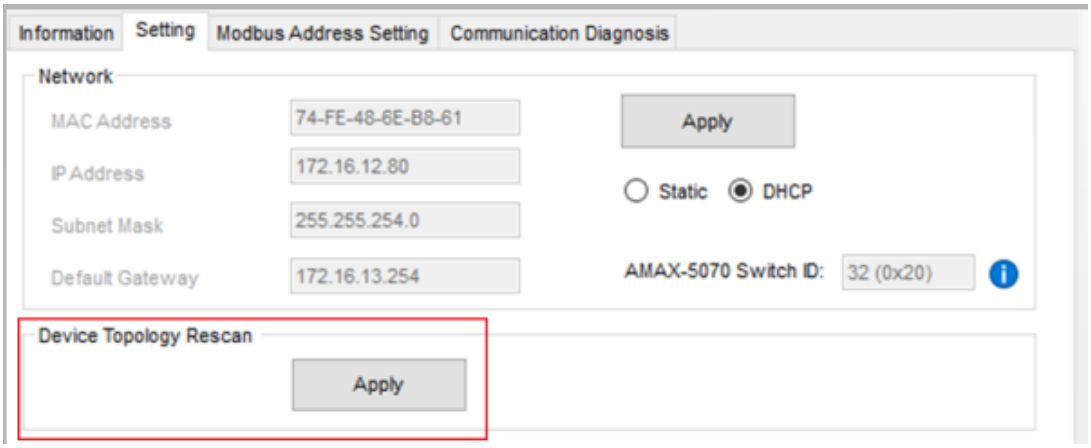

Figure 3.14 Rescan Function

If the AMAX-5070 connects to more than 255 SubDevices or the topology changed during the scan progress, the Utility will display Error (Figure 3.15).

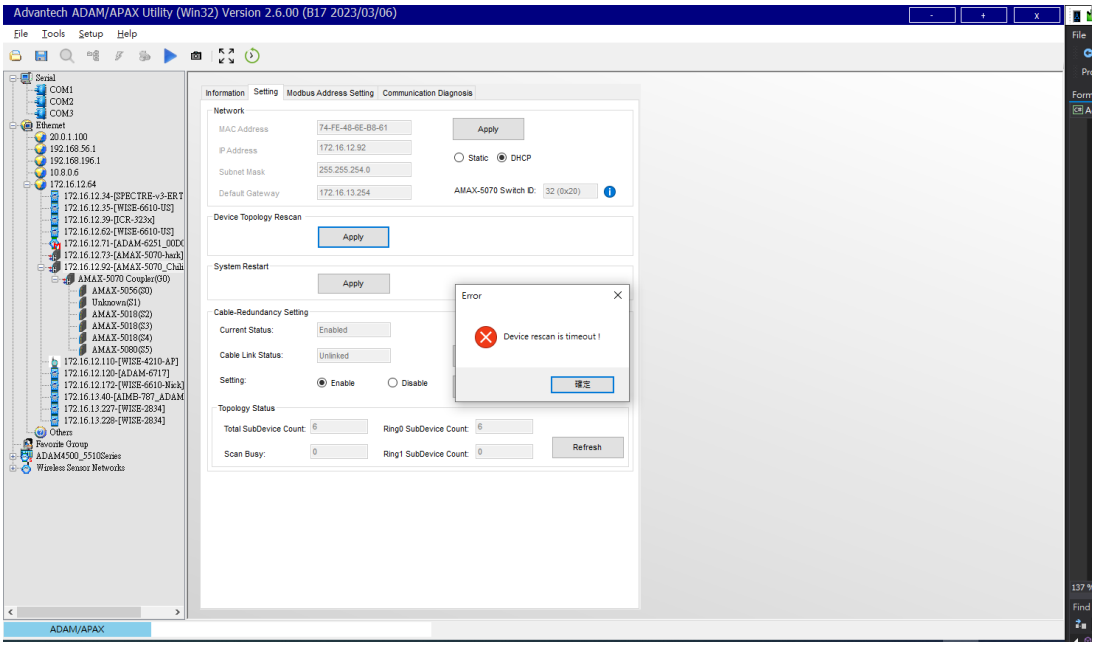

Figure 3.15 Time out

3.3.4 Restart the OS of the AMAX-5070

After clicking the **Apply** button, AMAX-5070 will rebooting the system (Figure 3.16).

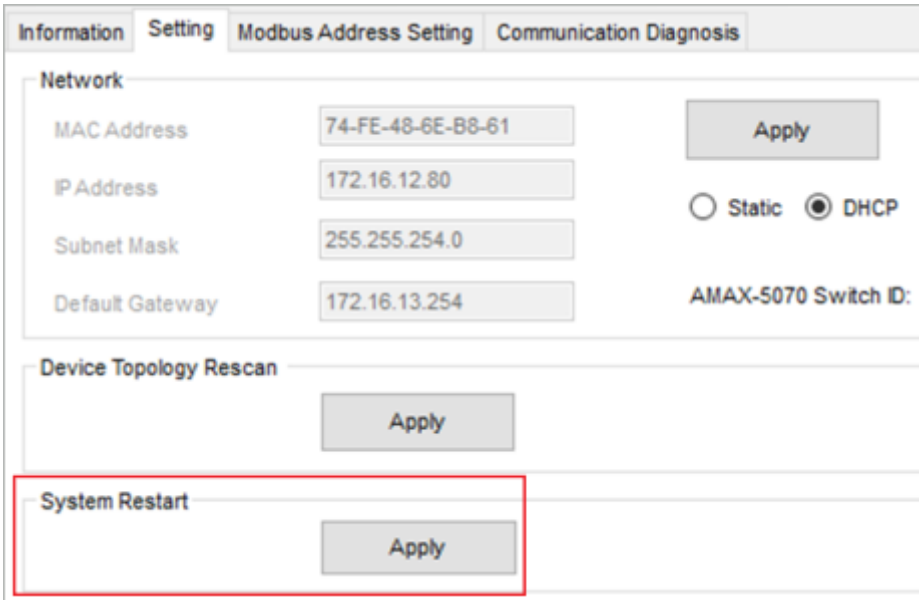

Figure 3.16 Restart the System

3.3.5 Cable Redundancy Configuration

The current status can be observed through Current Status and Cable Link Status, these two fields are not automatically updated, you need to click the Refresh button for acquiring the latest status.

User can select Enable/Disable button to select the cable redundancy and click the Apply to save setting (Figure 3.17).

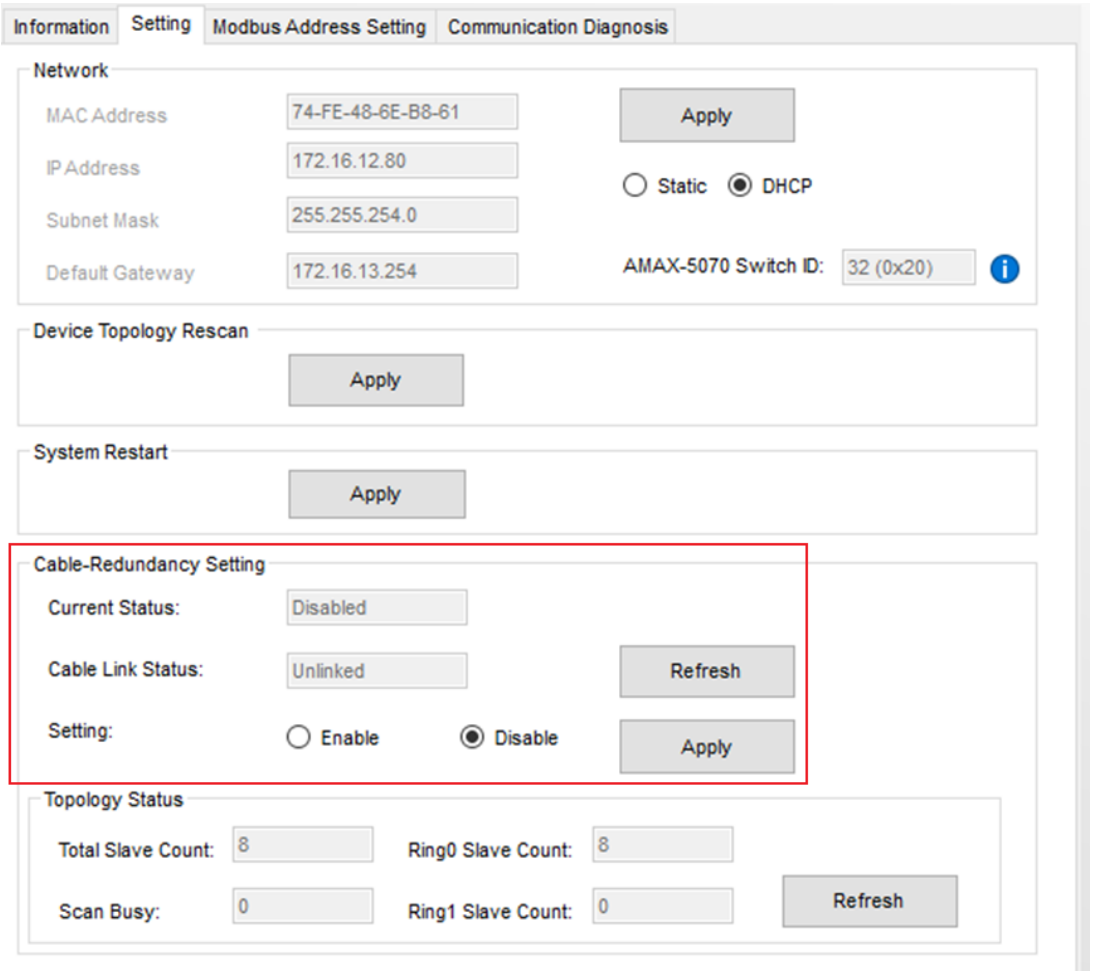

Figure 3.17 Cable Redundancy Setting

When set to Enable and click Apply, a notification pops up to remind the user to confirm the wiring (Figure 3.18).

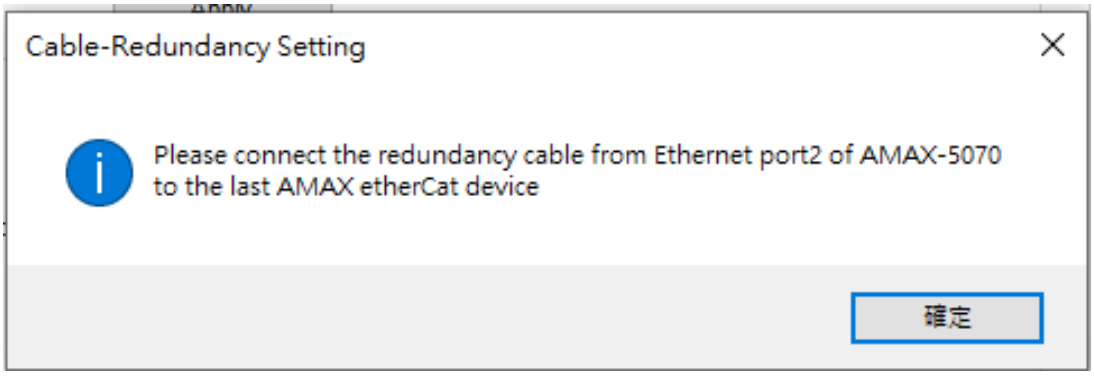

Figure 3.18 Cable Redundancy Notification for Wiring

And it informs the user of the upper time limit that may be consumed (Figure 3.19).

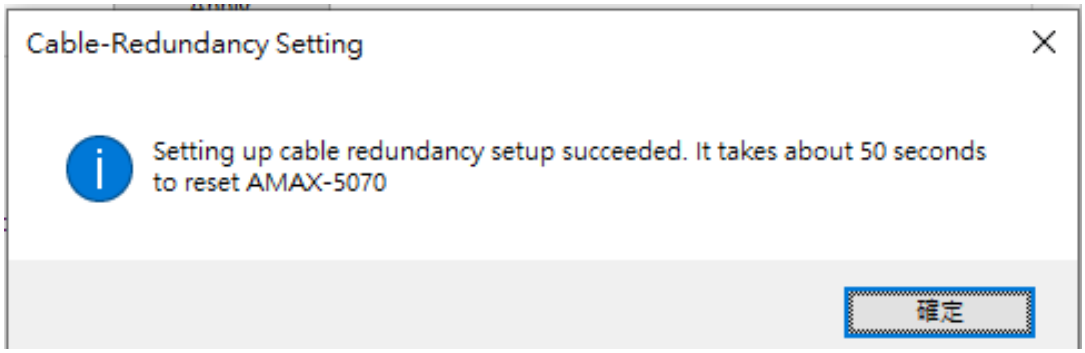

Figure 3.19 Cable Redundancy Notification for Estimated Reset Time

When Cable-Redundancy has been modified to Disable, the notification will remind users to remove the LAN 2 wiring.

3.3.6 Obtaining the Topology Status

This contains several bits of information (Figure 3.20):

1. Total SubDevice Count: The total number of SubDevices
2. Ring0 SubDevice Count: The number of SubDevices detected through Ethernet port1
3. Ring1 SubDevice Count: The number of SubDevices detected through Ethernet port2 (is only enabled in cable-redundancy if it has been set to “Enable”, otherwise the value would be set to 0.
4. Scan Busy: 0 for non-busy, 1 for busy (If Scan Busy value =1, AMAX-5070 internal system is working with each SubDevice for re-establishes the topology. At this time the SDO command doesn’t work, only the PDO data can operate).

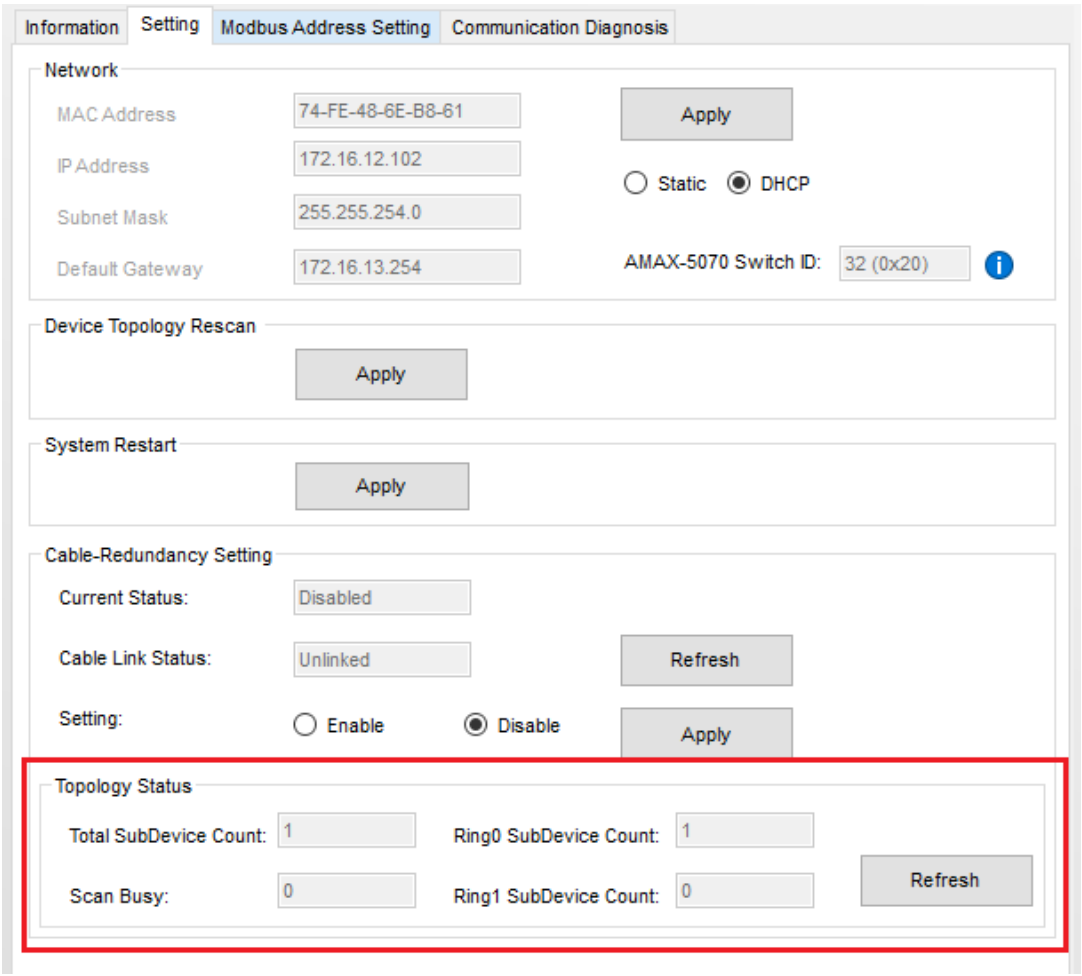

Figure 3.20 Topology Status

3.4 Modbus Address Setting

To adjust the Fixed Mode or Flexible Mode and obtain the corresponding Modbus addresses, click on Modbus Mapping.

For the AMAX-5070 device, the Modbus client address should always be set to Group 0 (G0), and it is not affected by the rotary switch on the device (as shown in Figure 3.21). But the rotary switch value will show on MainDevice.

However, for the AMAX-5074 device, both the Advantech Utility Group ID and Modbus client Device ID will automatically synchronize with the value set on the rotary switch (as indicated in Table 3.1). It's important to note that the AMAX-5079 device does not occupy a Modbus address (as depicted in Figure 3.22).

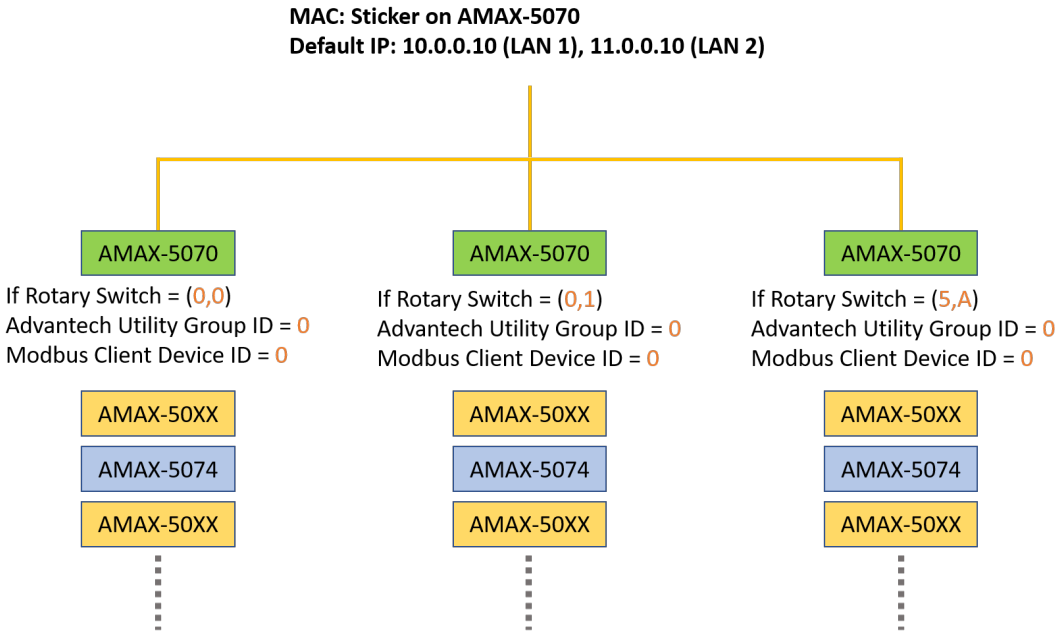

Figure 3.21 AMAX-5070 Modbus Client Address and Rotary Switch

Table 3.1: AMAX-5074 Group ID and Modbus Client Device ID

AMAX-5074 Rotary Switch [1]	Advantech Utility Group ID	Modbus Client Device ID
(0, 0)	0	0
(0, 1)	1	1
(0, A)	10	10
(4, C)	76	76

[1]: (SW2, SW1) = (0, A), then ID = 0x16 + 10x1 = 10

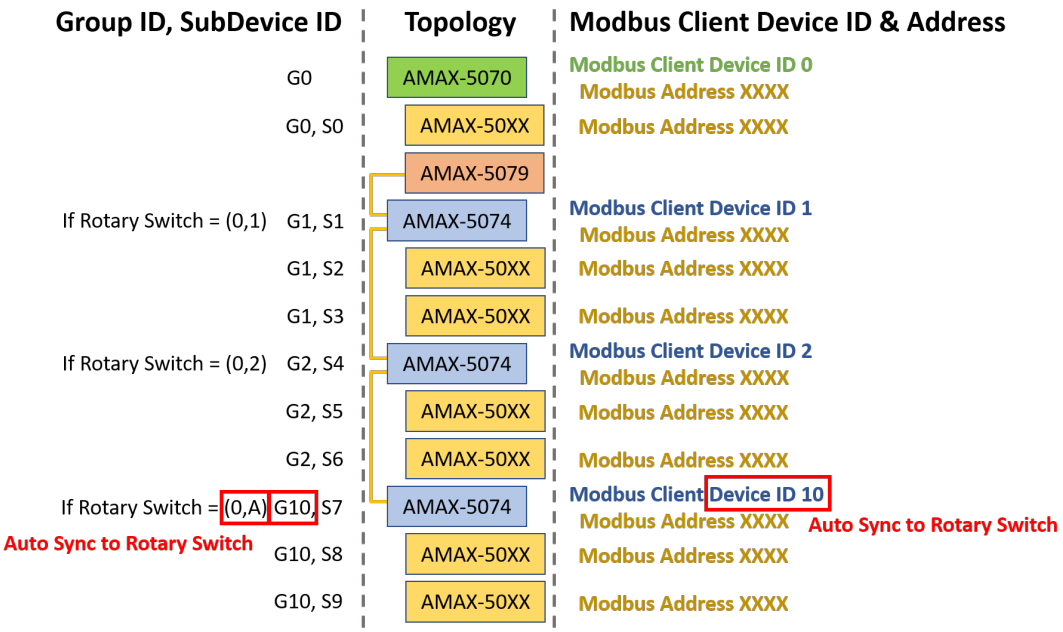

Figure 3.22 System Topology with Group ID and Device ID

Modbus address will change depending on which mode (Fixed Mode or Flexible Mode) or Group ID are currently used (Figure 3.23).

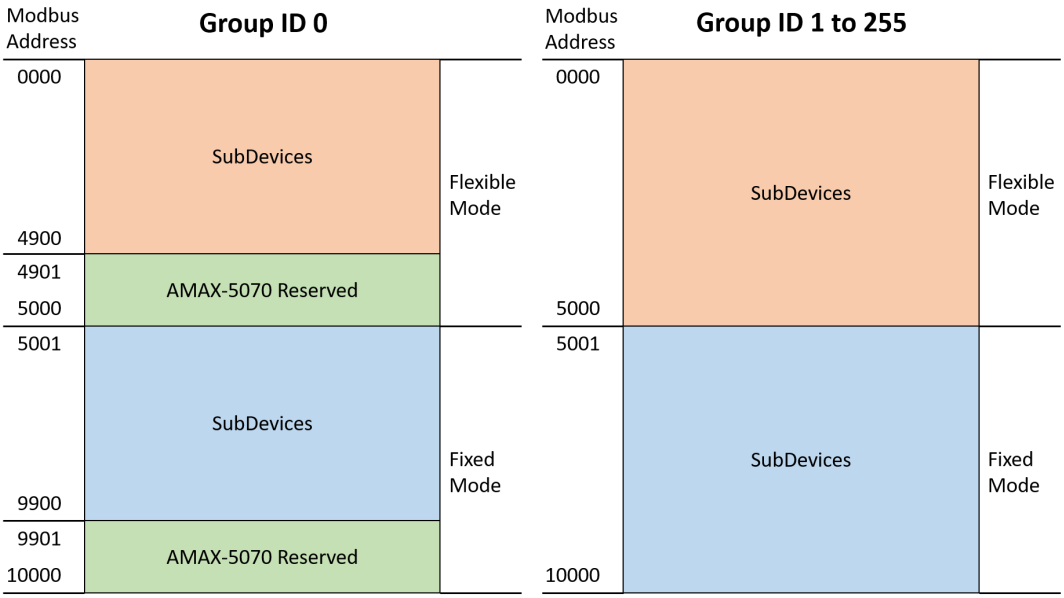

Figure 3.23 Modbus Address in Different Group ID and User Mode

3.4.1 Modbus Addresses for Connected Modules (Fixed Mode)

Click on Fixed Mode to obtain the current Modbus Address and Topology (Figure 3.24).

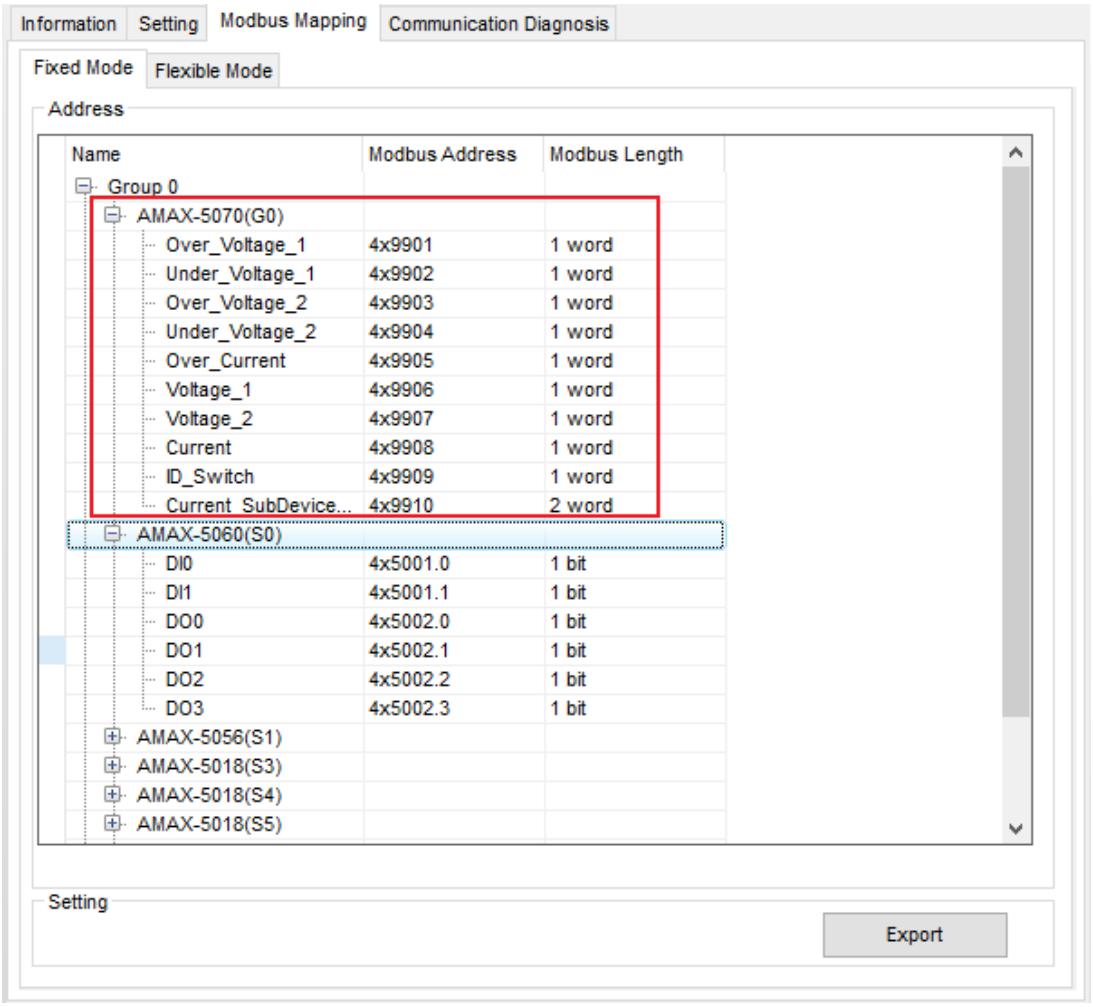

Figure 3.24 Modbus Address Setting Page

Modbus address will be reserved but won't display in the Advantech Utility because the unknown device occupies an address (Figure 3.25).

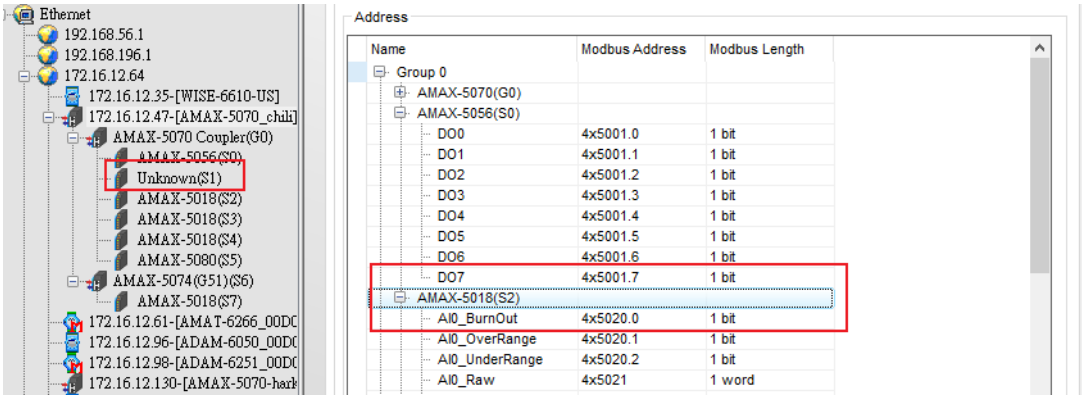

Figure 3.25 Modbus Address

3.4.2 Export the List of Modbus TCP Addresses for All Modules

Press the Export button to export the list with CSV file (Figure 3.26).

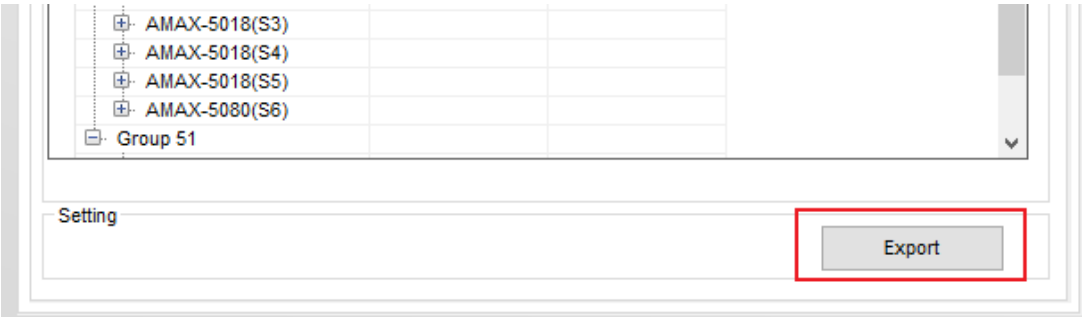

Figure 3.26 Export the ModBus TCP Address in Fixed Mode

The CSV file will be downloaded (Figure 3.27).

	A	B	C	D	E
1	StartAddress	AddressLength	DataType	ModuleName	AddressName
2	4x9901	1 word	UINT	AMAX-5070(G0)	Over_Voltage_1
3	4x9902	1 word	UINT	AMAX-5070(G0)	Under_Voltage_1
4	4x9903	1 word	UINT	AMAX-5070(G0)	Over_Voltage_2
5	4x9904	1 word	UINT	AMAX-5070(G0)	Under_Voltage_2
6	4x9905	1 word	UINT	AMAX-5070(G0)	Over_Current
7	4x9906	1 word	UINT	AMAX-5070(G0)	Voltage_1
8	4x9907	1 word	UINT	AMAX-5070(G0)	Voltage_2
9	4x9908	1 word	DINT	AMAX-5070(G0)	Current
10	4x9909	1 word	UINT	AMAX-5070(G0)	ID_Switch
11	4x9910	2 word	UINT	AMAX-5070(G0)	Current_SubDevice_Count
12	4x5001.0	1 bit	BOOL	AMAX-5060(S0)	DI0
13	4x5001.1	1 bit	BOOL	AMAX-5060(S0)	DI1
14	4x5002.0	1 bit	BOOL	AMAX-5060(S0)	DO0
15	4x5002.1	1 bit	BOOL	AMAX-5060(S0)	DO1
16	4x5002.2	1 bit	BOOL	AMAX-5060(S0)	DO2
17	4x5002.3	1 bit	BOOL	AMAX-5060(S0)	DO3
18	4x5003.0	1 bit	BOOL	AMAX-5056(S1)	DO0
19	4x5003.1	1 bit	BOOL	AMAX-5056(S1)	DO1
20	4x5003.2	1 bit	BOOL	AMAX-5056(S1)	DO2
21	4x5003.3	1 bit	BOOL	AMAX-5056(S1)	DO3
22	4x5003.4	1 bit	BOOL	AMAX-5056(S1)	DO4
23	4x5003.5	1 bit	BOOL	AMAX-5056(S1)	DO5
24	4x5003.6	1 bit	BOOL	AMAX-5056(S1)	DO6
25	4x5003.7	1 bit	BOOL	AMAX-5056(S1)	DO7

Figure 3.27 Modbus TCP Addresses and Modules List in CSV File (Fixed Mode)

3.4.3 Modbus Addresses for Connected Modules (Flexible Mode)

The Flexible Mode will merge the Subdevices based on the functions and features. The catalog will be hidden if it doesn't have any modules.

DO Control
AO Control
Counter Control
DI Status
AO Status
AI Status
Counter Status
System Status

Modbus address will display in Flexible Mode, click the Flexible Mode tab in the Modbus Address Setting (Figure 3.28).

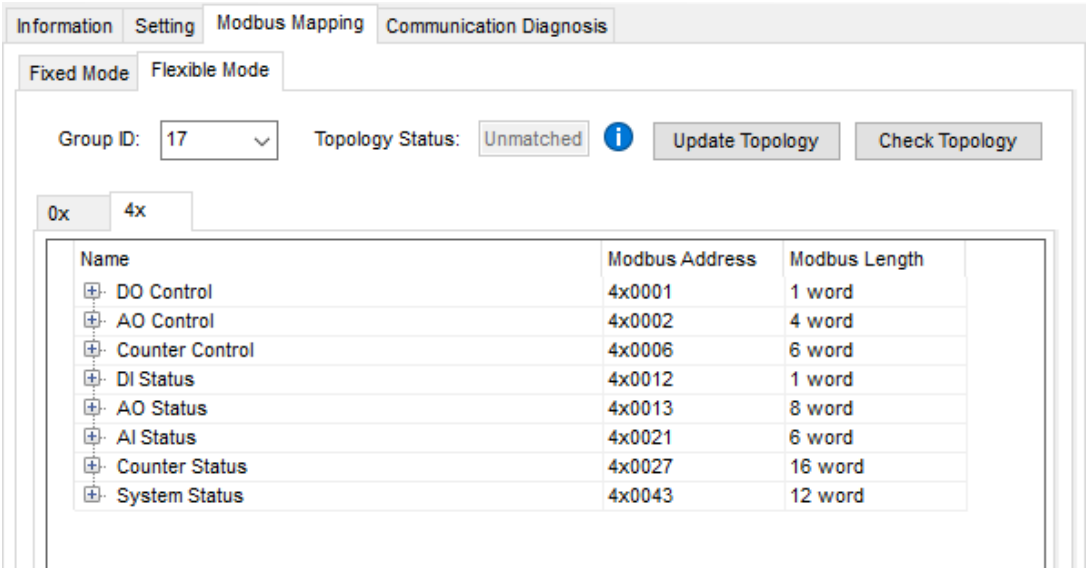

Figure 3.28 Flexible Mode

Flexible mode is used Group ID to manage the SubDevices. Change the Group ID number to modify the SubDevice configurations in this group. The Coil Status will be displayed in 0x tab (data size is bit, e.g. DI value, burnout status) and the Holding Register in 4x tab (data size is word) (Figure 3.29).

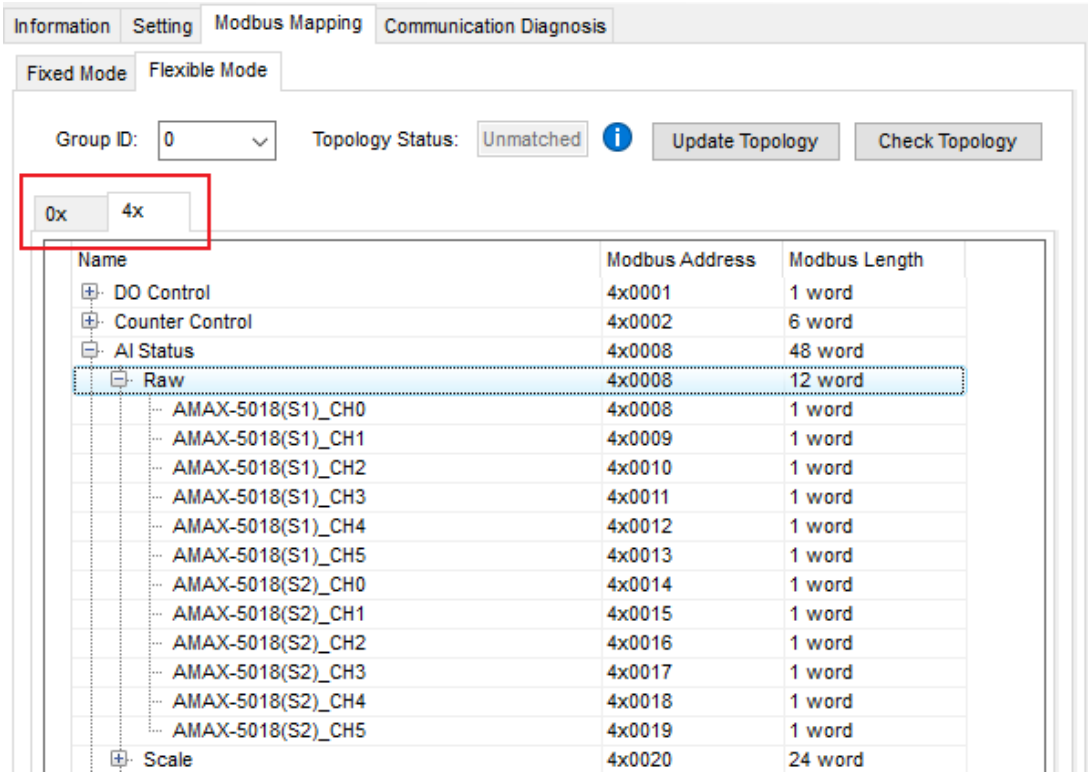

Figure 3.29 Modbus Coil Status and Holding Register

The Topology Status indicates whether the system is in flexible mode and if the Modbus address mapping is functioning correctly. Initially, the status is "Unmatched" which means that the AMAX-5070 device was not mapping the Modbus address. To save the current mapping and topology, click on the "Update" button.

After the update, the Topology Status will display either "Matched" if the current topology matches the saved one, or "Unmatched" if the current topology is different from the saved one (Figure 3.30).

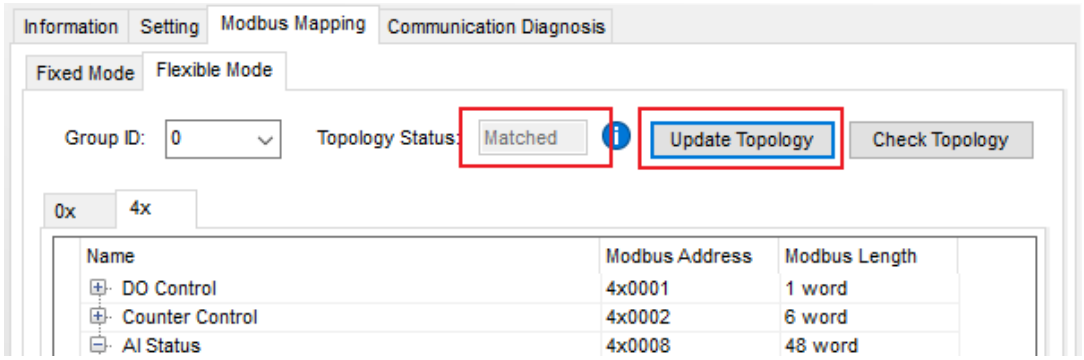

Figure 3.30 Flexible Mode Mapping Topology Status

After saving the current topology, click on "Check topology" to load the saved topology. If the current topology doesn't match the saved one, the system will mark the unmatched SubDevices in red (Figure 3.31).

After clicking on "Update Topology", the saved topology can be updated with any changes made to the current configuration. This allows you to save the latest changes to the topology.

On the other hand, clicking on "Clear Config file" will clear the saved configuration file, effectively removing the saved topology. This action will reset the configuration to its initial state before any changes were made.

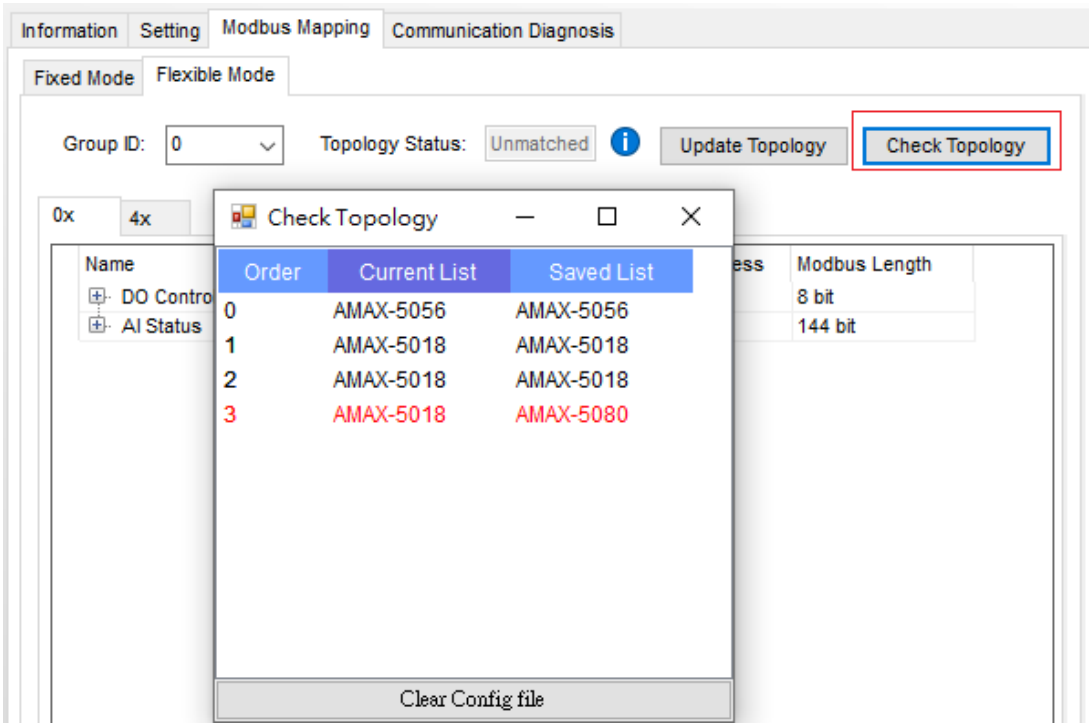

Figure 3.31 Check the Unmatched SubDevices

3.4.4 Export the List of Modbus TCP Addresses for All Modules (Flexible Mode)

Press the Export button to export the list with CSV file (Figure 3.32).

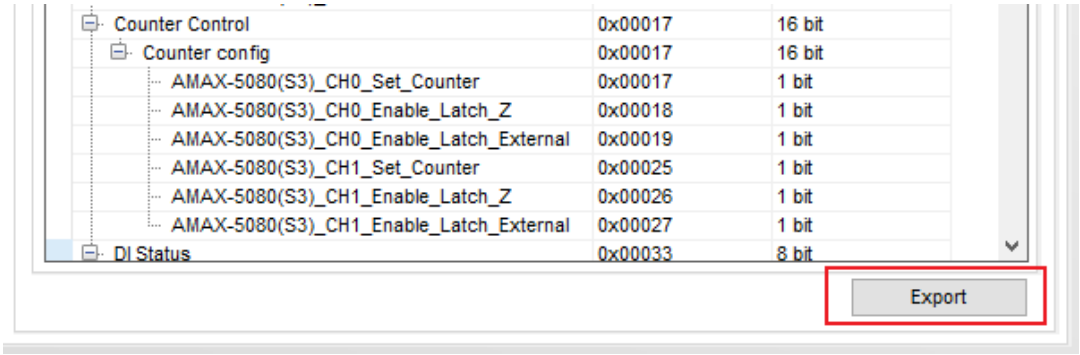

Figure 3.32 Export the ModBus TCP Address in Flexible Mode

The CSV file will be downloaded (Figure 10).

	A	B	C	D	E	F
1	StartAddress	AddressLength	DataType	Catalog	Function	Device Description
2	0x0001	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH0
3	0x0002	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH1
4	0x0003	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH2
5	0x0004	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH3
6	0x0005	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH4
7	0x0006	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH5
8	0x0007	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH6
9	0x0008	1 bit	BOOL	DO Control	Value	AMAX-5056(S0)_CH7
10	0x0009	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH0_Set_Counter
11	0x0010	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH0_Enable_Latch_Z
12	0x0011	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH0_Enable_Latch_External
13	0x0017	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH1_Set_Counter
14	0x0018	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH1_Enable_Latch_Z
15	0x0019	1 bit	BOOL	Counter Control	Counter config	AMAX-5080(S4)_CH1_Enable_Latch_External
16	0x0025	1 bit	BOOL	AI Status	BurnOut	AMAX-5018(S1)_CH0_BurnOut
17	0x0026	1 bit	BOOL	AI Status	BurnOut	AMAX-5018(S1)_CH0_OverRange
18	0x0027	1 bit	BOOL	AI Status	BurnOut	AMAX-5018(S1)_CH0_UnderRange

Figure 3.33 Modbus TCP Addresses and Modules List in CSV File (Flexible Mode)

3.4.5 Identify the Modules of Abnormal Communication

The modules can be highlighted if they communicate abnormally, click the Mark Communication Status under Communication Diagnosis page. The module will be highlighted by a yellow flag if the error counter goes over Error Threshold Middle value, or red flag if the error counter goes over the Error Threshold High value (Figure 3.34).

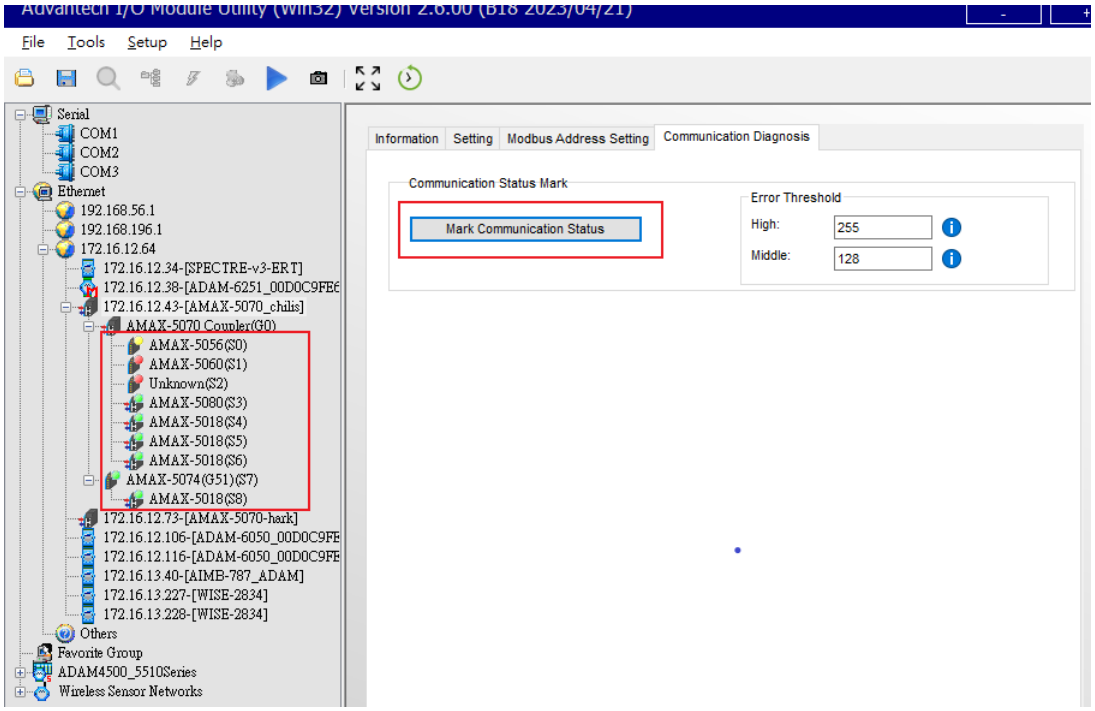

Figure 3.34 Mark Communication Status

If the module disconnects, it will be marked with "?" (Figure 3.35).

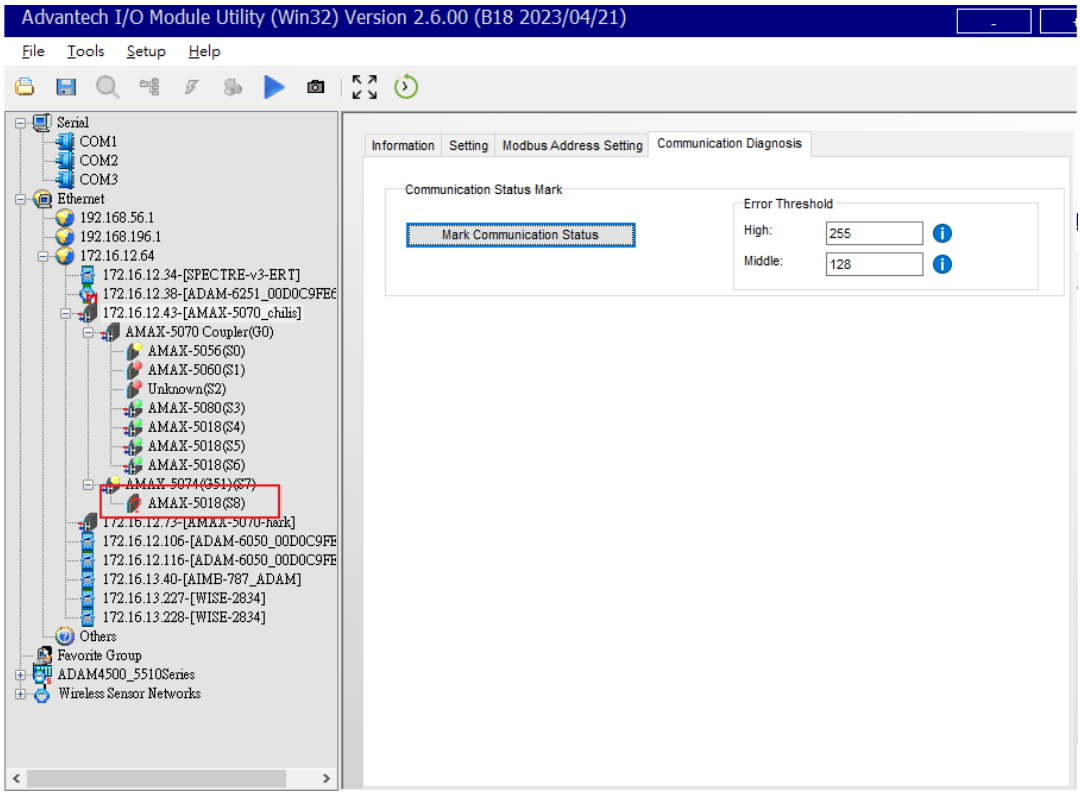

Figure 3.35 Mark Communication Status when Module disconnection

Chapter 4

Coupler and SubDevice Configuration

4.1 Coupler and SubDevice Configuration

4.1.1 Device Categories

It can be roughly divided into three categories (Figure 4.1):

- Coupler Modules with segmentation groups (AMAX5070, AMAX5074).
- Modules that don't have segmentation groups (SubDevices).
- Unknown SubDevices.

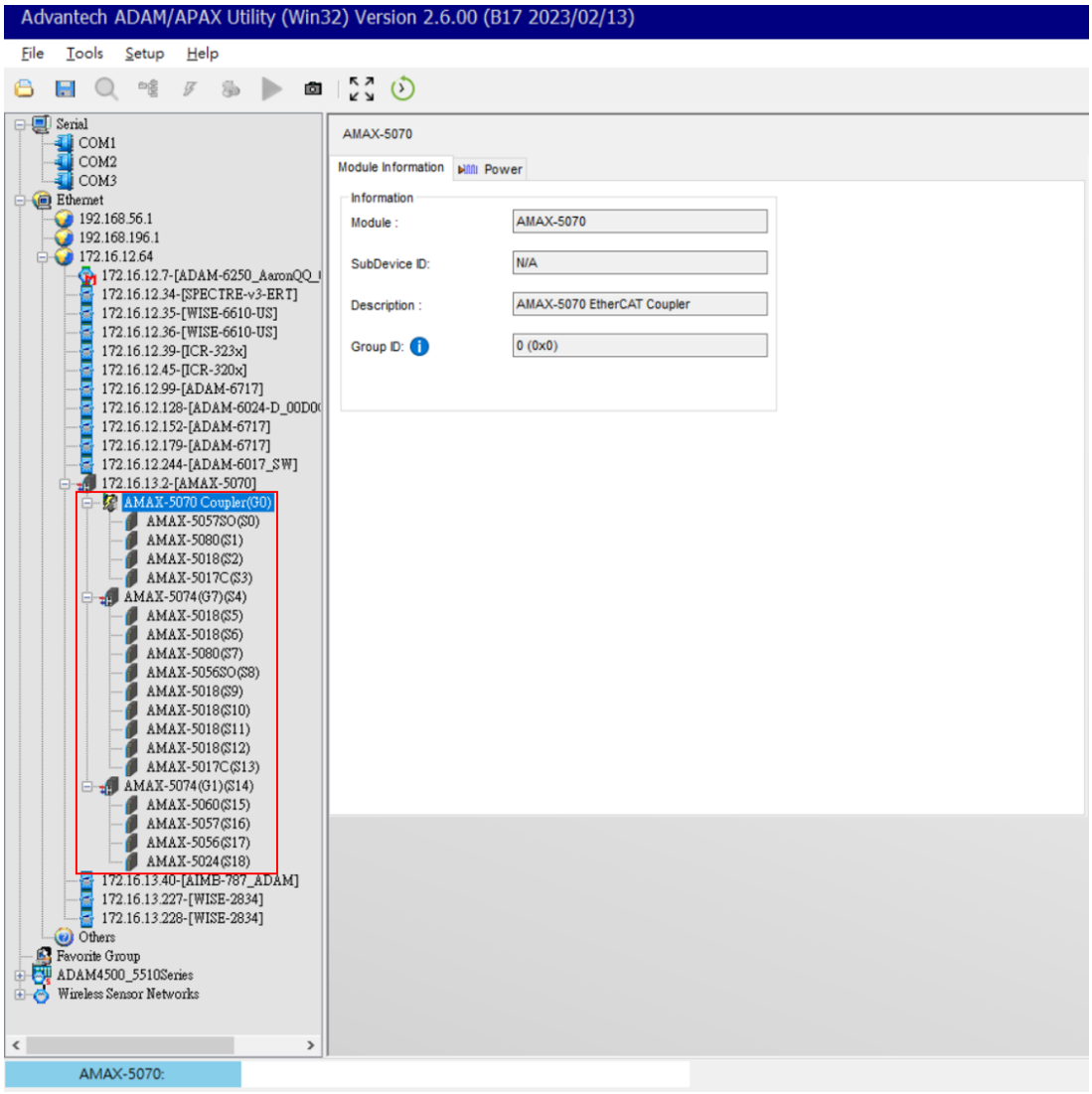

Figure 4.1 Device Categories

4.1.1.1 Coupler

Module Name, SubDevice ID (N/A as default), Description, and Group ID can be found in the Module Information page (Figure 4.2).

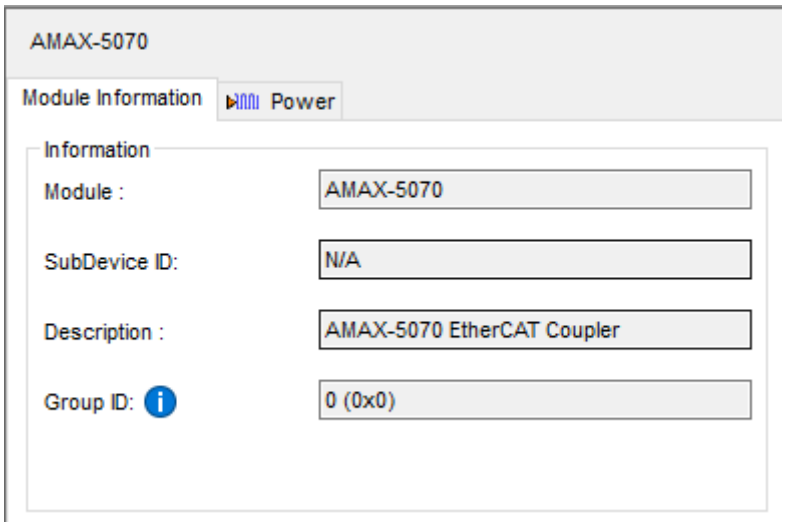

Figure 4.2 Coupler or Coordinator Module Information

4.1.1.2 SubDevice

In the SubDevice, information includes Module, SubDevice ID, and Description (Figure 4.3).

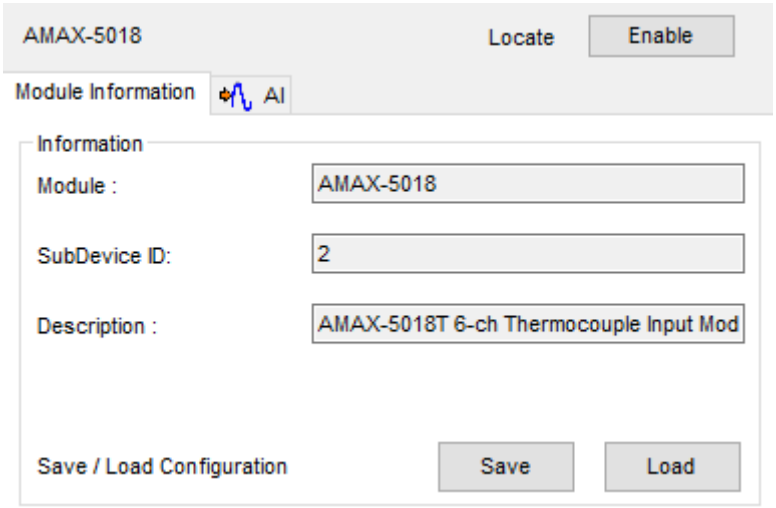

Figure 4.3 SubDevice Information

4.1.1.3 Unknown SubDevices

For Unknown SubDevice, only SubDevice ID can be found (Figure 4.4).

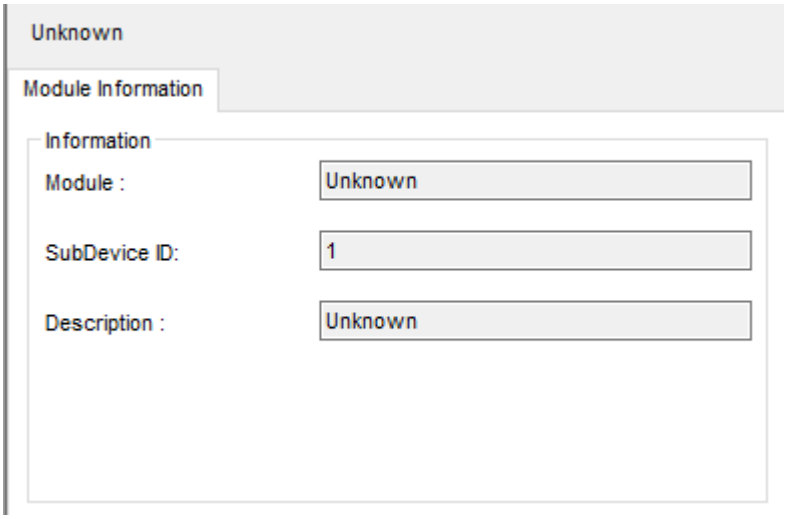

Figure 4.4 Unknown Module Information

4.1.2 Storing and Loading Configurations

When the IO settings of a SubDevice are configurable, regardless of the number of sub-pages, the Load/Save configuration operation can be performed in the Module Information tab. For example, the configuration of the AI tab in the following figure can be saved or loaded through the button (Figure 4.5).

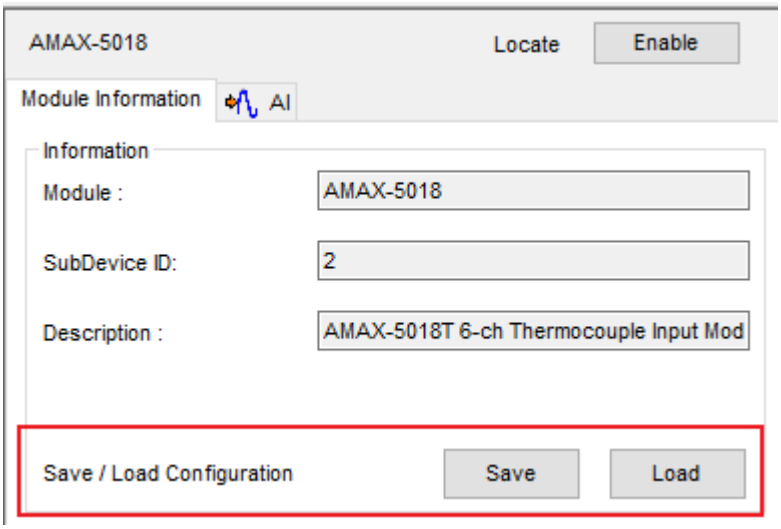

Figure 4.5 Save and Load Configuration

The configuration of DI/DO settings shown in the diagram can also be saved or loaded through the Save or Load button (Figure 4.6).

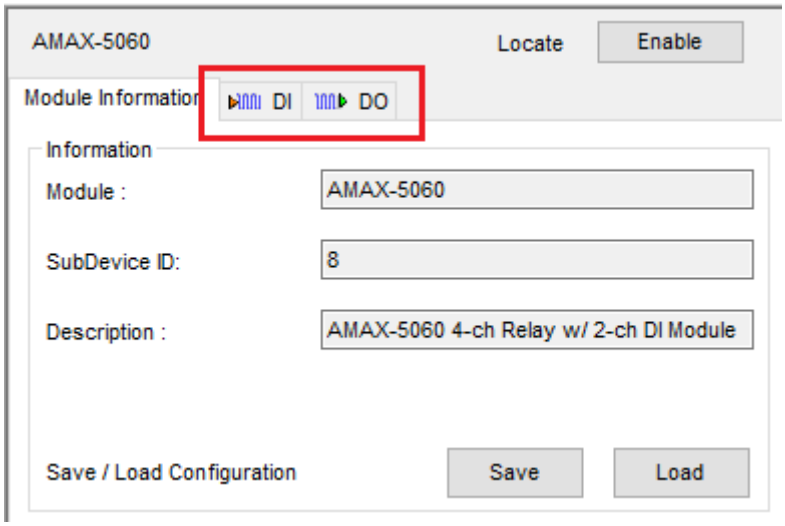

Figure 4.6 DI/DO Configuration

For SubDevices that do not support the save/load configuration feature, the Save and Load buttons will be hidden (Figure 4.7. For example, the AMAX-5056SO only supports setting and reading DO values, but doesn't support any DO configuration functions such as safety functions.

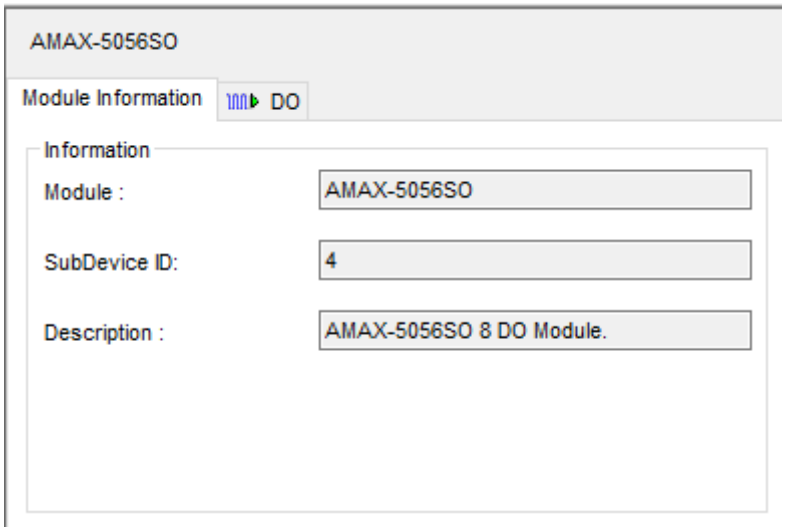

Figure 4.7 Example of Not Supported SubDevice UI

4.1.3 Locate SubDevices

Users can turn on the locate LED on the SubDevice when click the Enable button; click againg will turn off the locate LED (Figure 4.8.

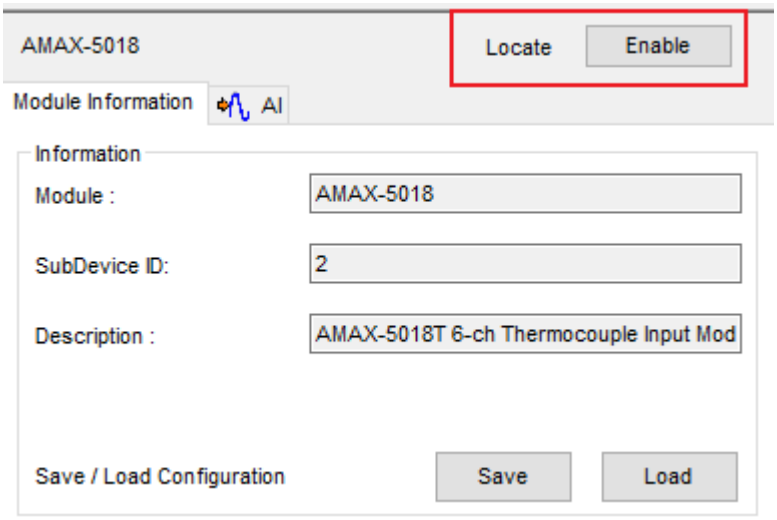

Figure 4.8 Locating SubDevice Function

For devices that do not support the Locate feature, the locate button is hidden (Figure 4.9).

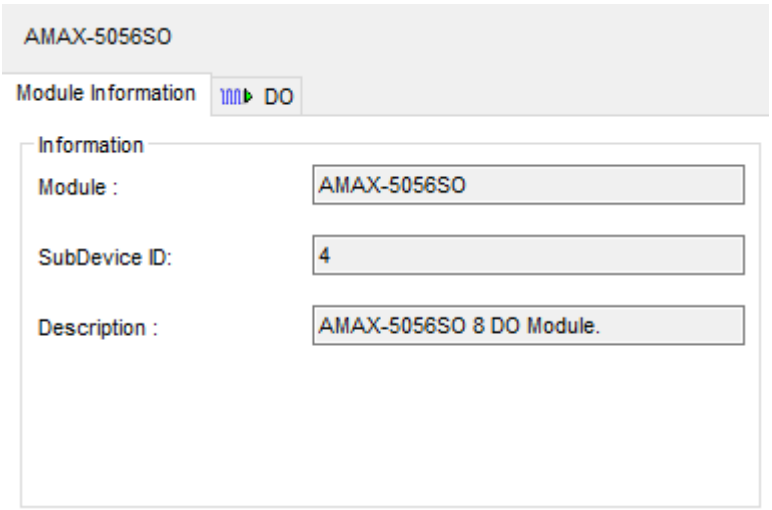

Figure 4.9 SubDevice without LED Locate Function

4.2 Obtain and Configure Coupler and SubDevice

4.2.1 Obtain Power SubDevices Status

Through the Power tab, you can get the current/voltage related status (Figure 4.10). The Channel information will display the value of current, voltage1, voltage2 and the corresponding Modbus address.

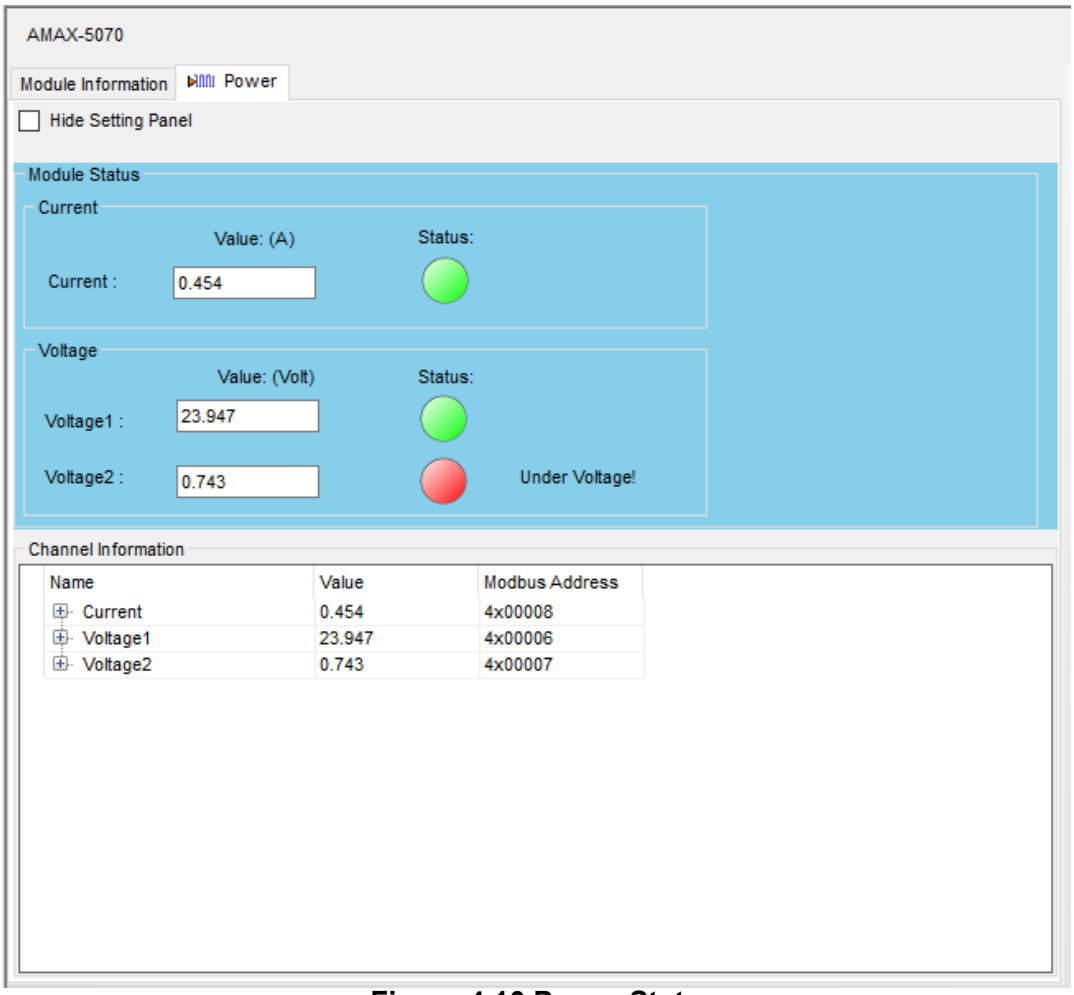

Figure 4.10 Power Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.11).

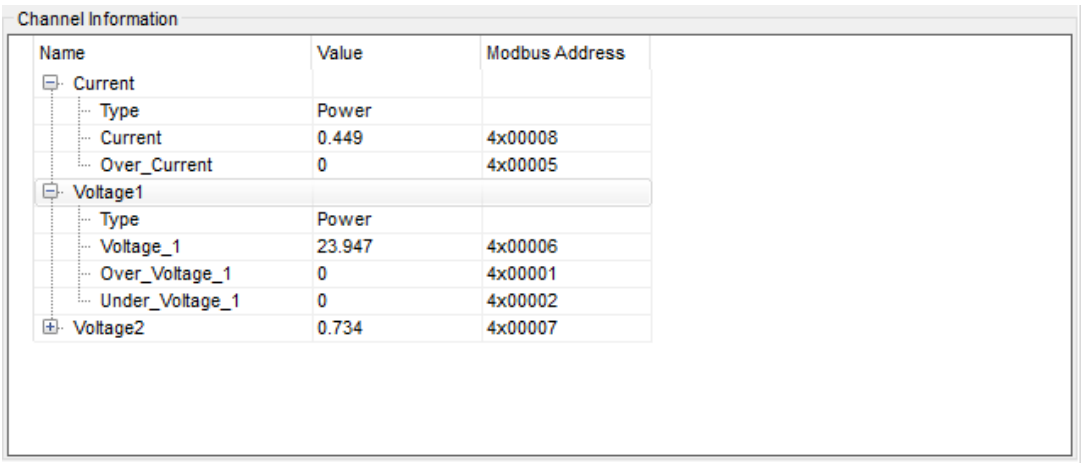

Figure 4.11 Power Status and Modbus Address Information

4.2.2 Analogue Input SubDevices

4.2.2.1 Obtain Analogue Input Status

Through the AI tab, users can obtain the AI-related status and the Modbus address in the channel information (Figure 4.12).

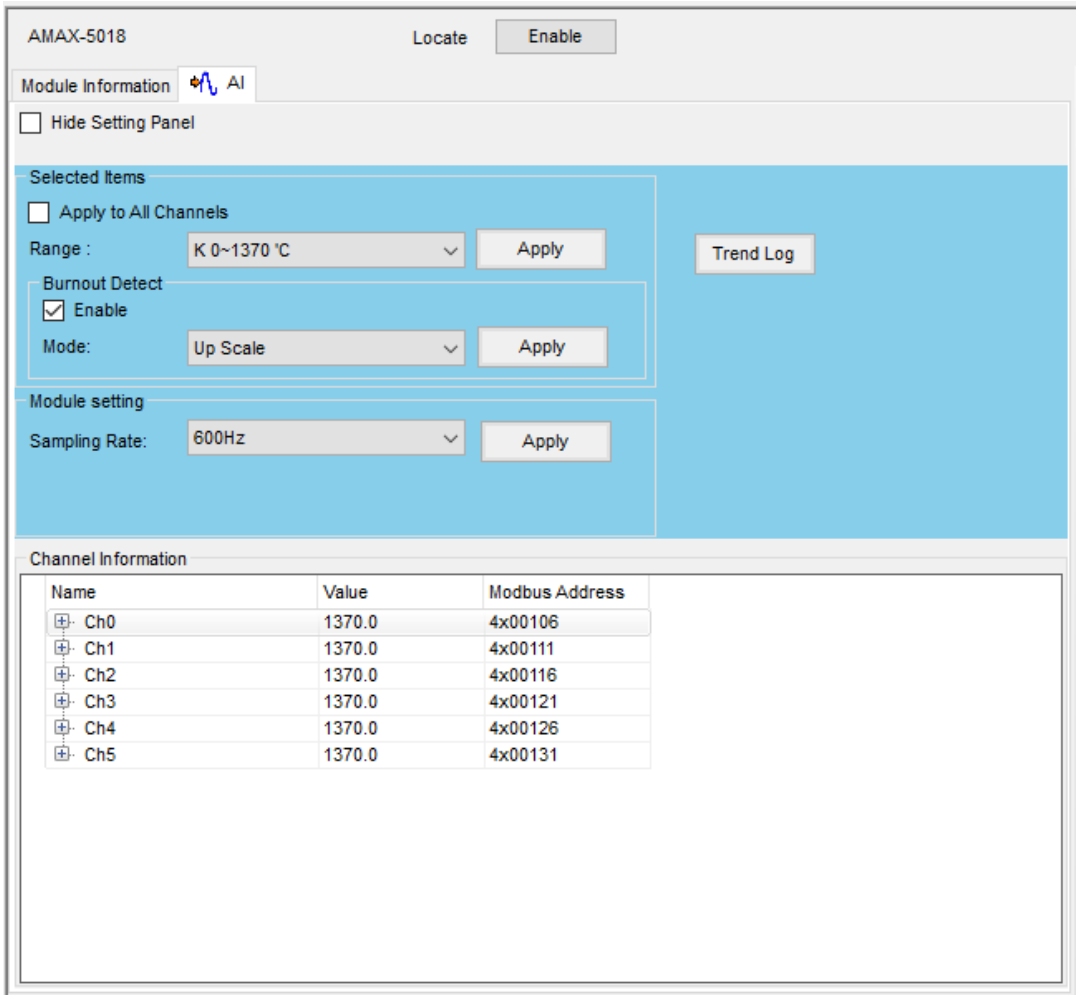

Figure 4.12 Analogue Input Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.13).

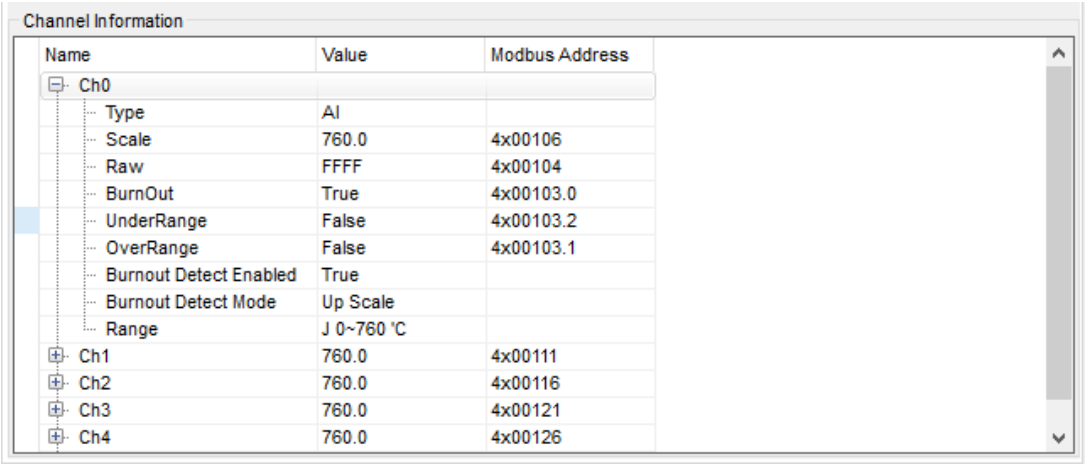

Figure 4.13 Analogue Input Value and Modbus Address Information

4.2.2.2 Configure Analogue Input

Channel information can be configured in different range. For example, we want to set the channel 1 input range from K to ±2.5V.

1. Expand the channel's tree and the selected Items will be shown in the blue area (Figure 4.14).

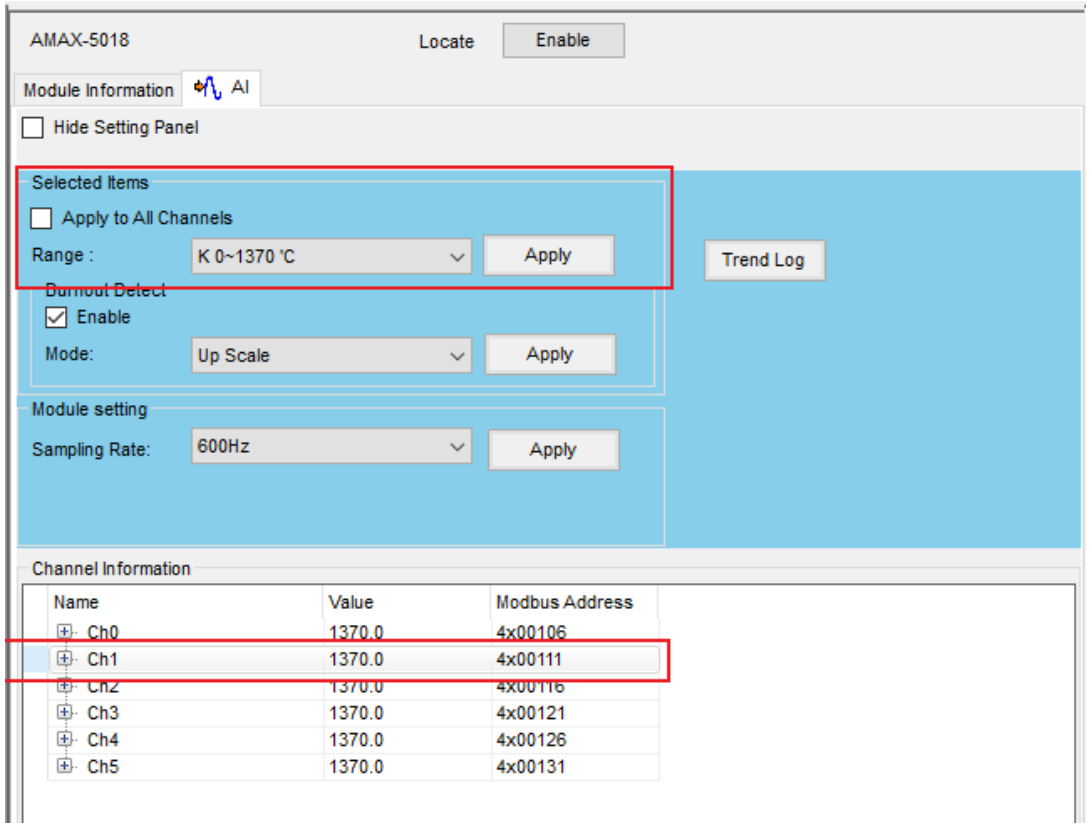

Figure 4.14 Expand the Tree and Change the AMAX-5018 Range

2. Select the range ±2.5V and click the Apply button. Users also can apply the setting to all channels (Figure 4.15).

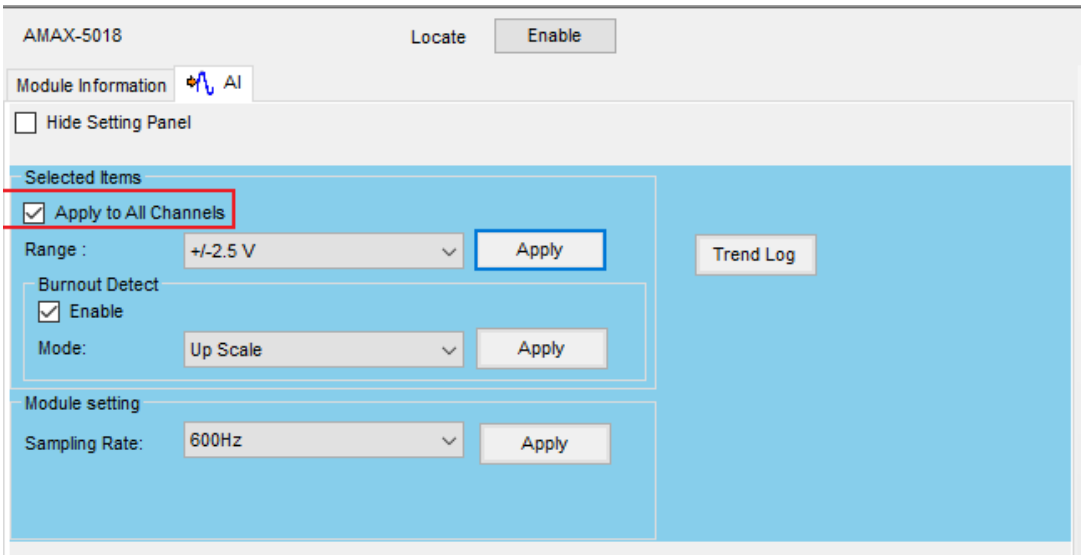

Figure 4.15 Apply the Change for All Channels of This SubDevice

4.2.3 Analogue Output SubDevices

4.2.3.1 Obtain Analogue Output Status

Through the AO tab, users can obtain the AO-related status and the Modbus address in the channel information (Figure 4.16).

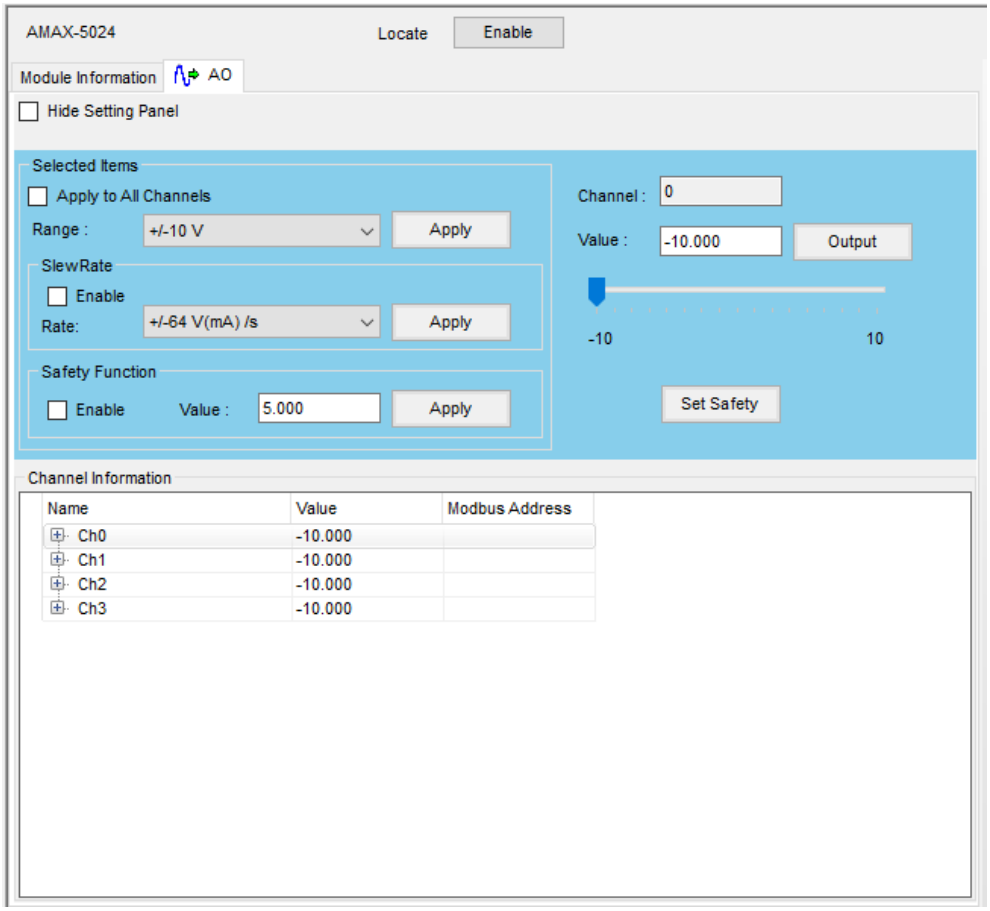

Figure 4.16 Analogue Output Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.17).

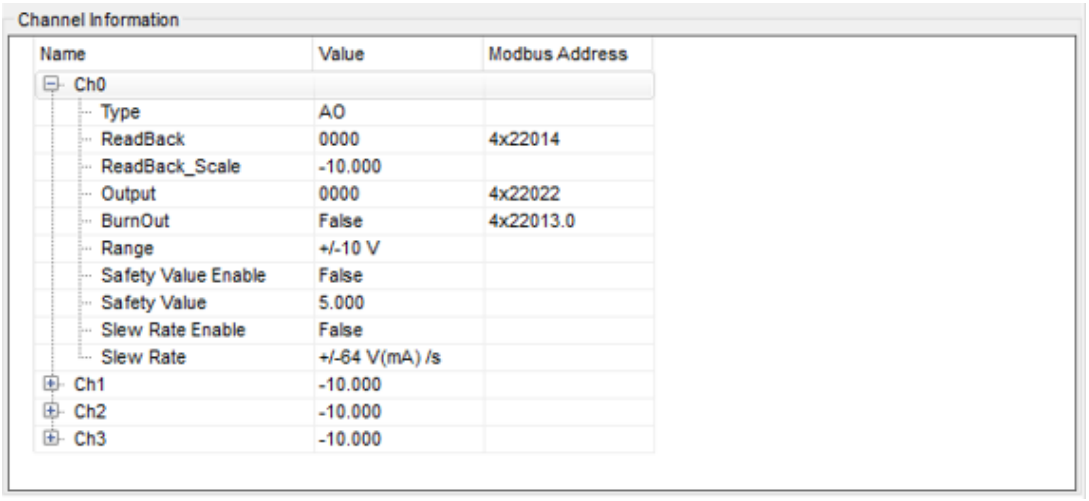

Figure 4.17 Analogue Output Value and Modbus Address Information

4.2.3.2 Configure Analogue Output

Channel information can be configured in different ranges. For example, if we want to change the channel 0 input range (Figure 4.18).

1. Expand the channel's tree and the selected Items will be shown on the blue area.
2. Select the ranges you want and click the Apply button. Users also can apply the setting to all channels.

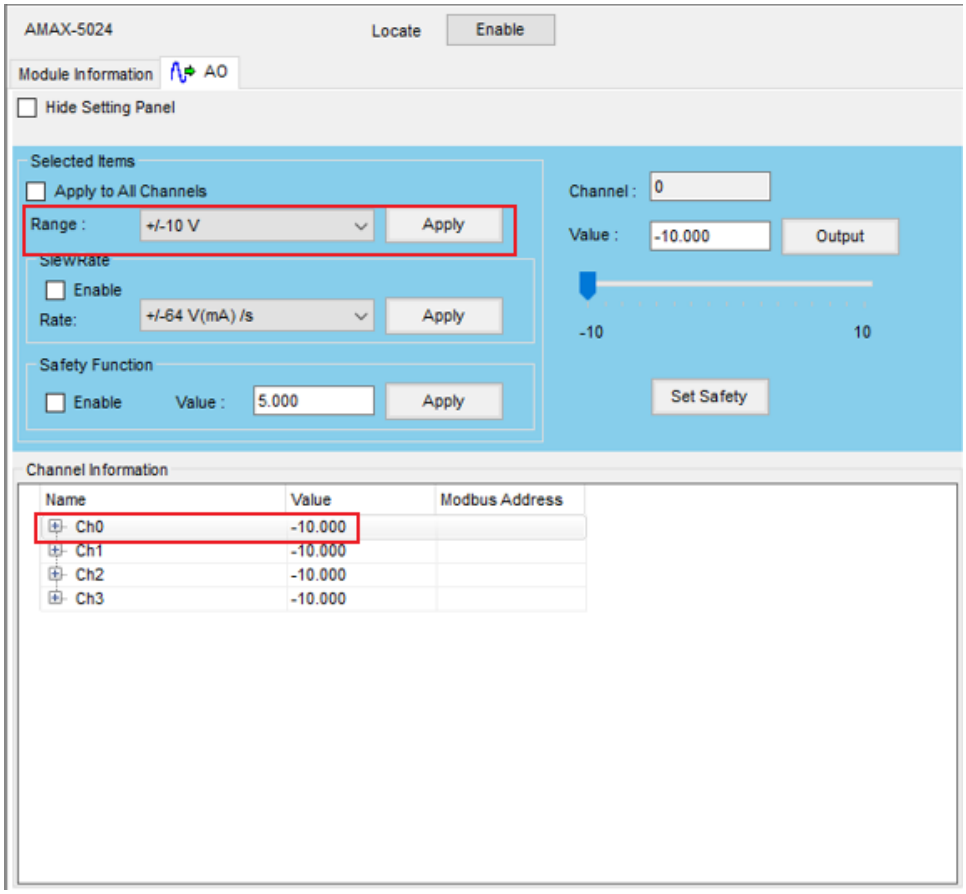

Figure 4.18 Expand the Tree and Change the AMAX-5024 Range

4.2.4 Digital Input SubDevices

4.2.4.1 Obtain Digital Input Status

Through the DI tab, user can obtain the DI-related status and the Modbus address in the channel information (Figure 4.19).

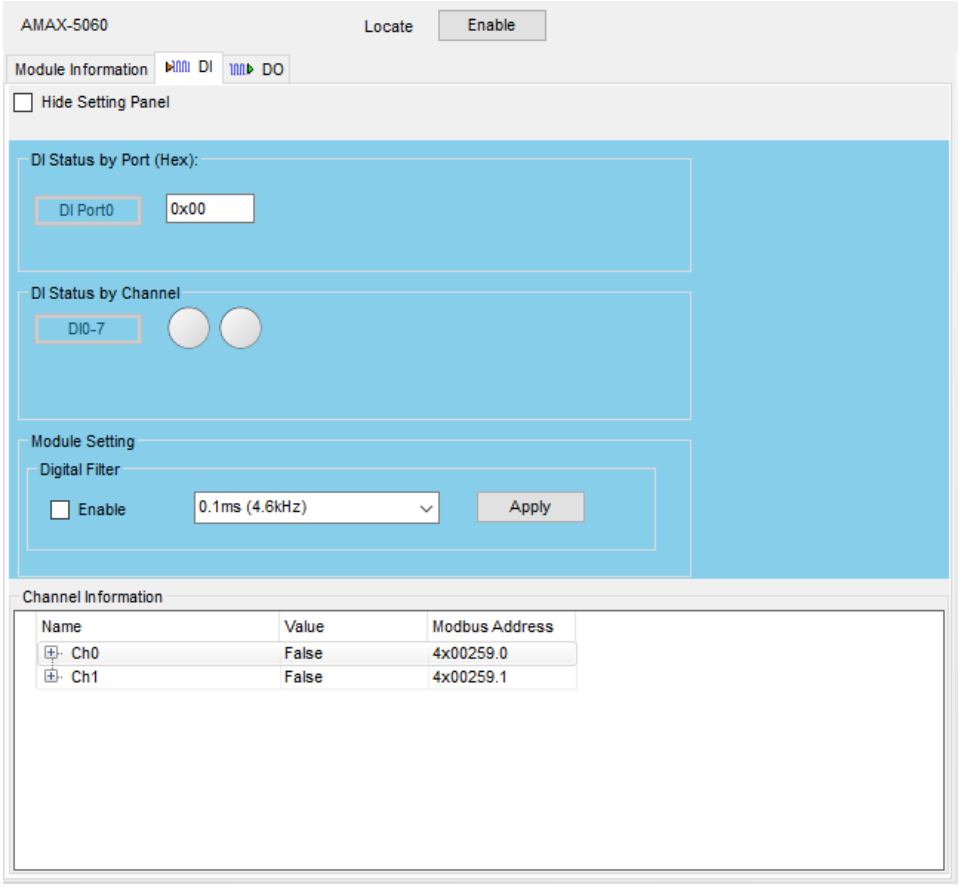

Figure 4.19 Digital Input Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.20).

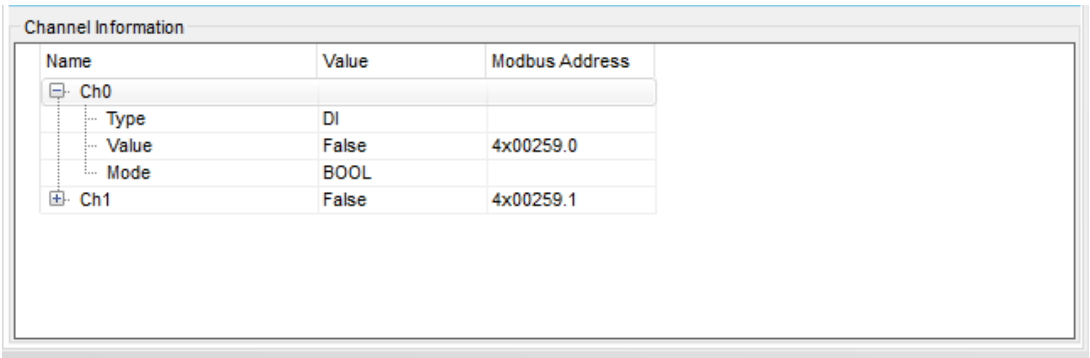

Figure 4.20 Digital Input Value and Modbus Address Information

4.2.4.2 Configure Digital Input

Channel information can be configured in different range. For example, if we want to Enable the channel 0 digital filter (Figure 4.21).

1. Expand the channel's tree and the selected Items will be shown on the blue area.
2. Enable the Digital Filter and Select the range you want. Next, click the Apply button.

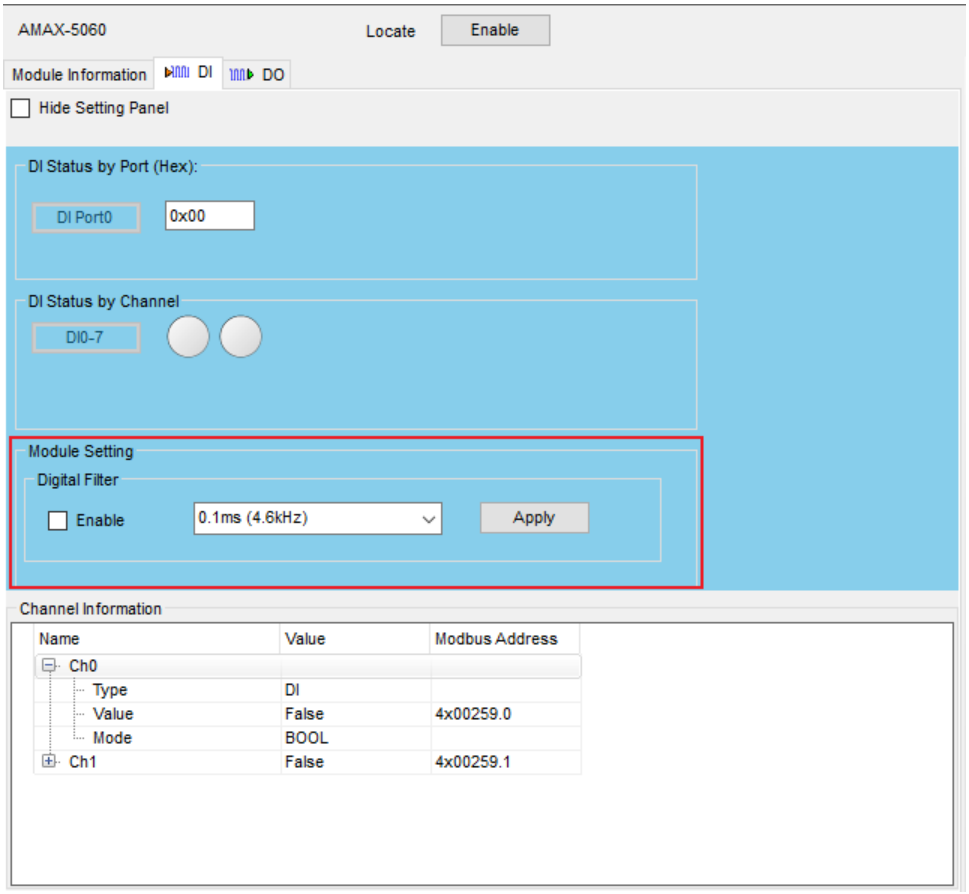

Figure 4.21 Enable AMAX-5060 Digital Filter

4.2.5 Digital Output SubDevices

4.2.5.1 Obtain Digital Output Status

Through the DO tab, users can obtain the DO-related status and the Modbus address in the channel information (Figure 4.22).

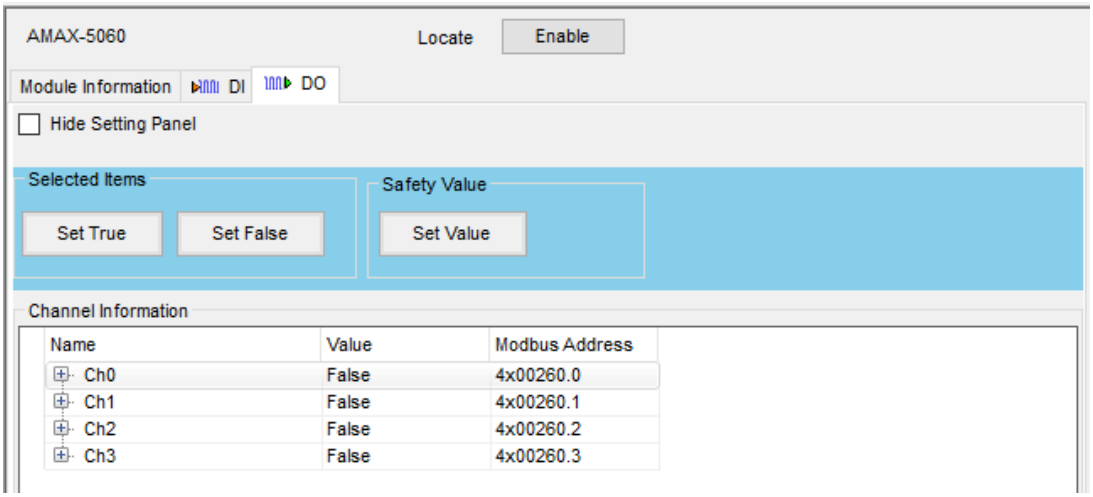

Figure 4.22 Digital Output Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.23).

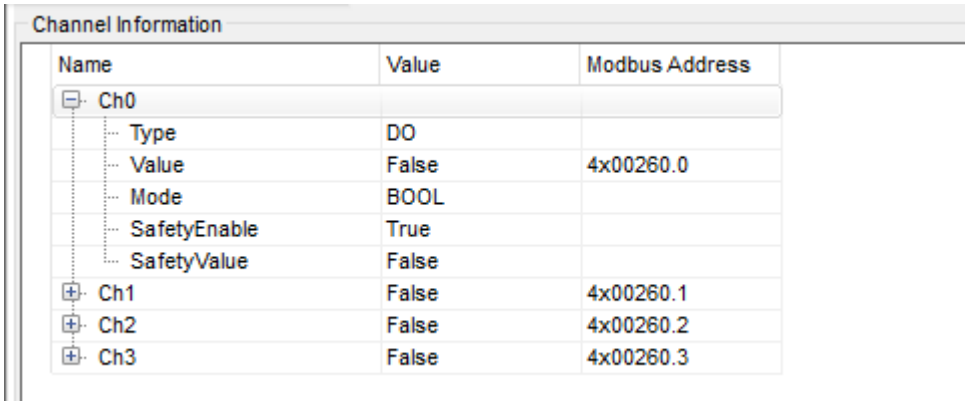

Figure 4.23 Digital Output Value and Modbus Address Information

4.2.5.2 Configurate Digital Output

Channel information can be configured in different ranges. For example, we want to set the channel 0 output status for high level (Figure 4.24).

1. Expand the channel's tree and the selected Items will be shown in the blue area.
2. Click the Set True button.

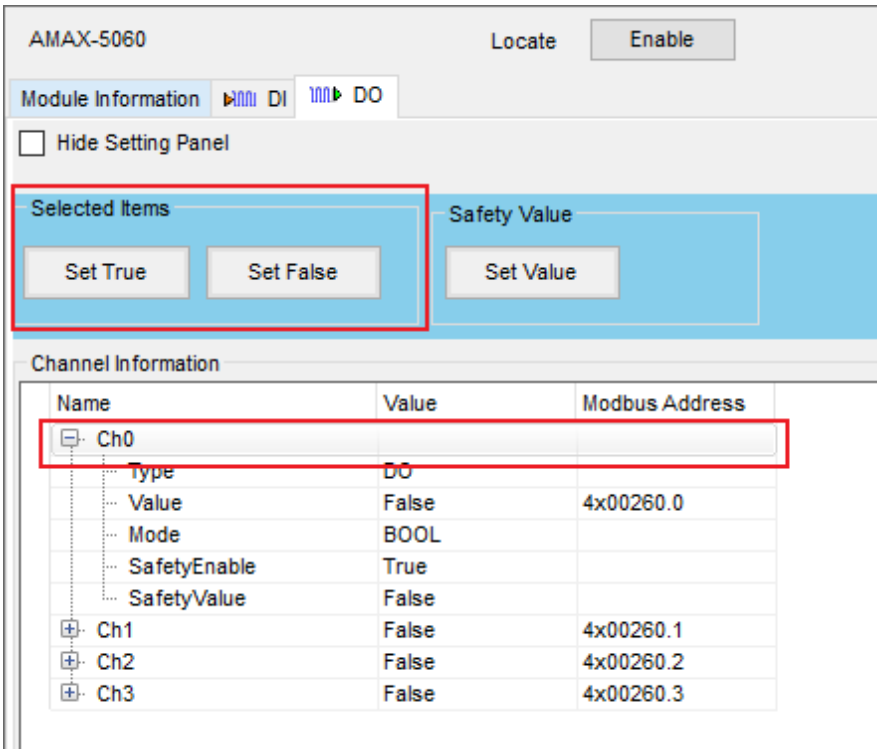

Figure 4.24 Change AMAX-5060 Digital Output Status

4.2.5.3 Configure Safety Value

Supported modules: AMAX-5060.

The safety function is SubDevice will output the safety value when modules disconnects from MainDevice. The DO safety value can be set when you click the Set Value button (Figure 4.25).

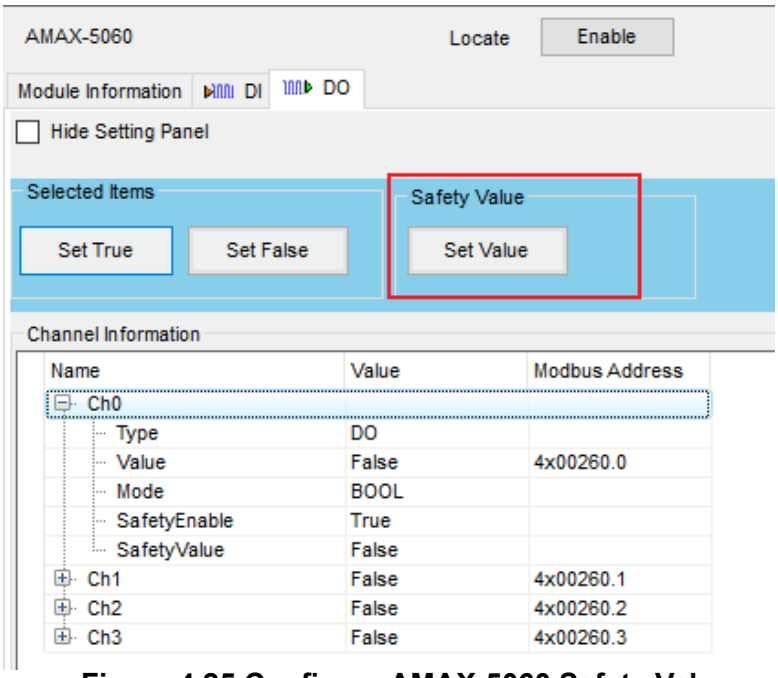

Figure 4.25 Configure AMAX-5060 Safety Value

After clicking the Set Value button, the Safety Setting page will be displayed, and individual channels can be checked for Enable/Safety State. Click the Apply button to save the changes (Figure 4.26).

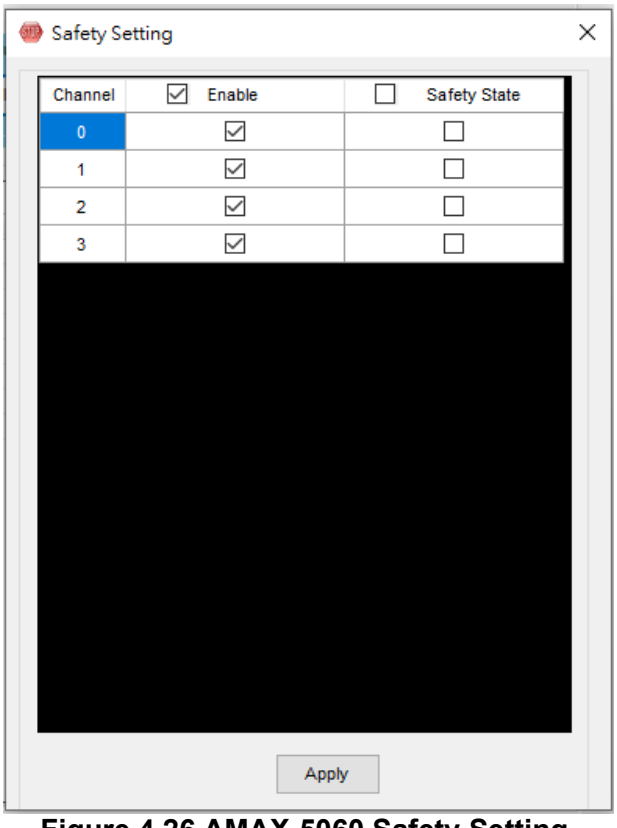

Figure 4.26 AMAX-5060 Safety Setting

4.2.6 Counter/Encoder SubDevices

4.2.6.1 Obtain Counter/Encoder State

Through the CNT tab, user can obtain the CNT-related status and the Modbus address in the channel information (Figure 4.27).

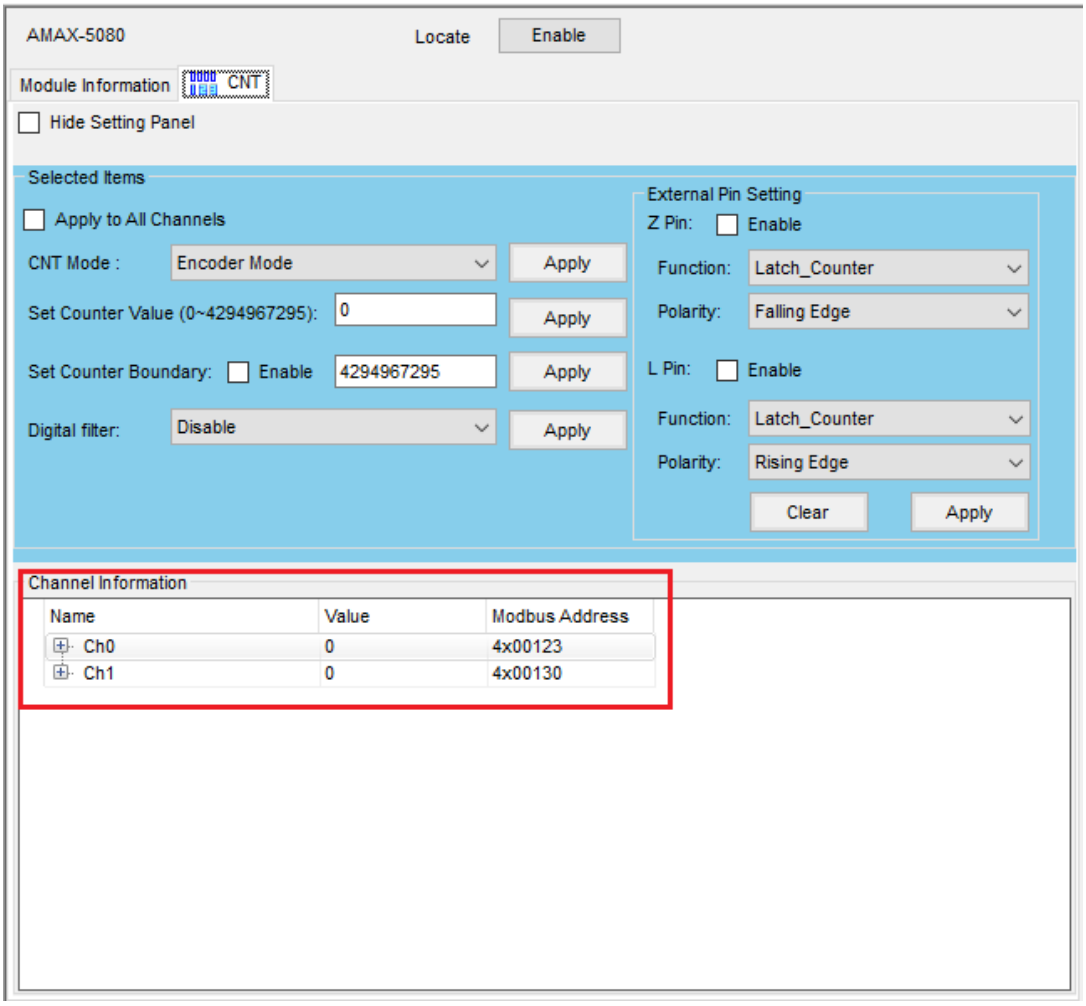

Figure 4.27 Counter and Encoder Status

The tree in Channel Information can be expanded to show more detailed information (Figure 4.28).

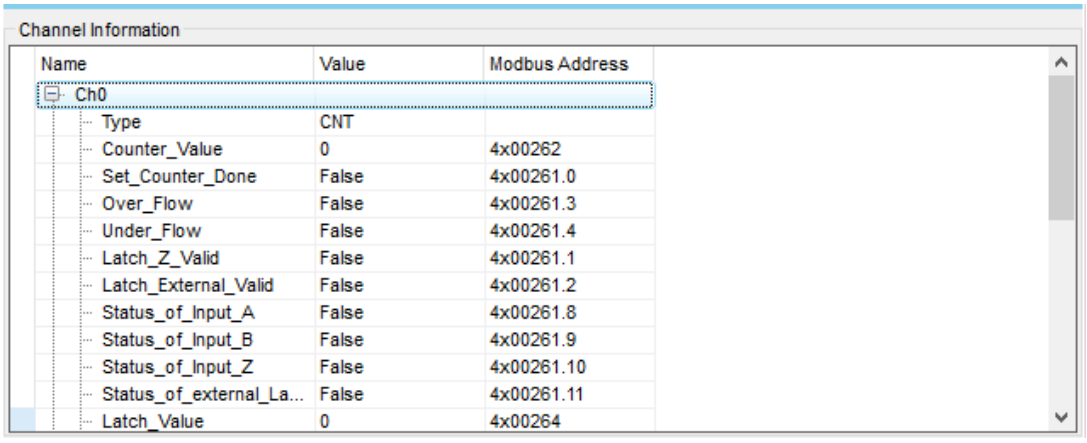

Figure 4.28 Counter/Encoder and Modbus Address Information

4.2.6.2 Configure Counter/Encoder

Channel information can be configured in different mode for one channel or all channels.

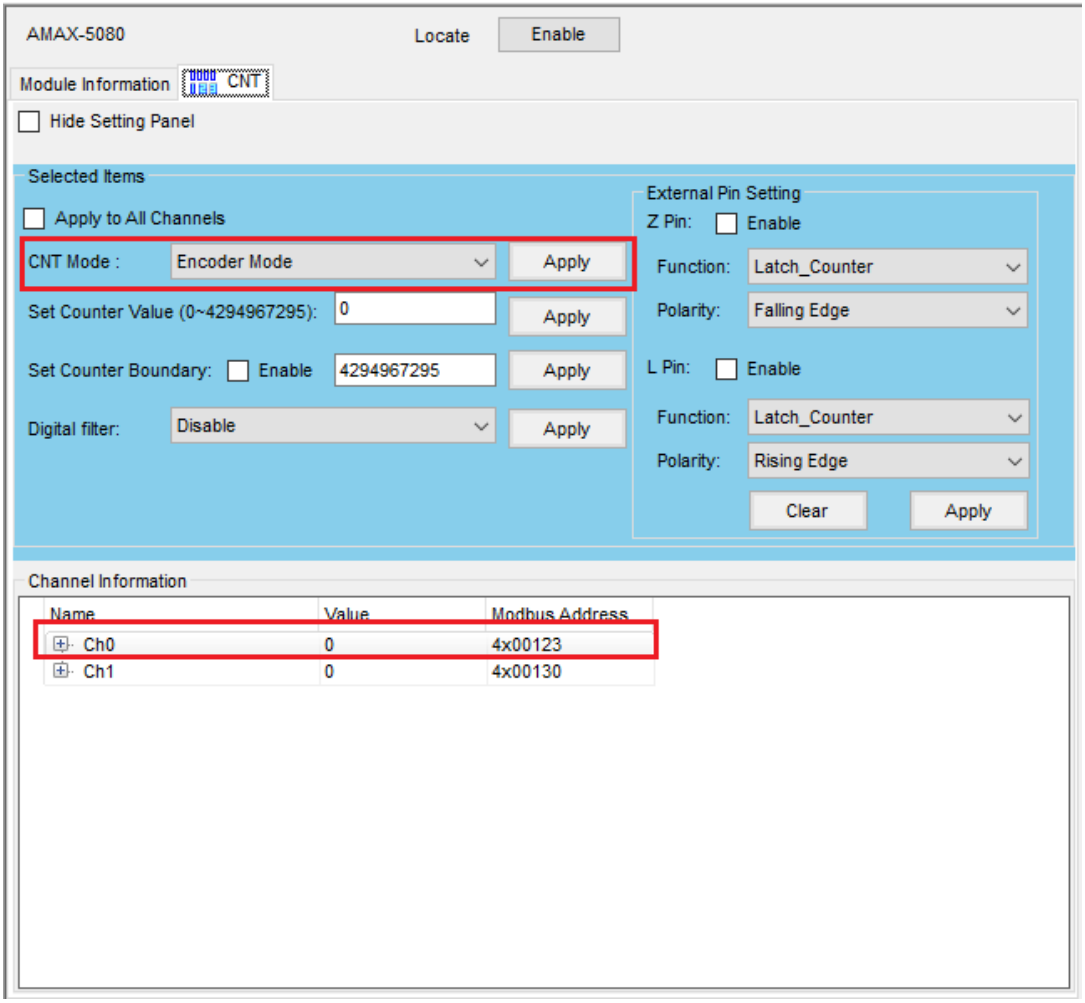

Figure 4.29 Change AMAX-5080 CNT Mode

External Pin Setting can be set to Latch Counter or Reset Counter. Check the Enable box to apply the function setting. The Latch Value can be found in the Channel Information if the Latch Counter Value is enabled. If you would like to discard the current Latch Counter Value, please click the Clear button (Figure 4.30).

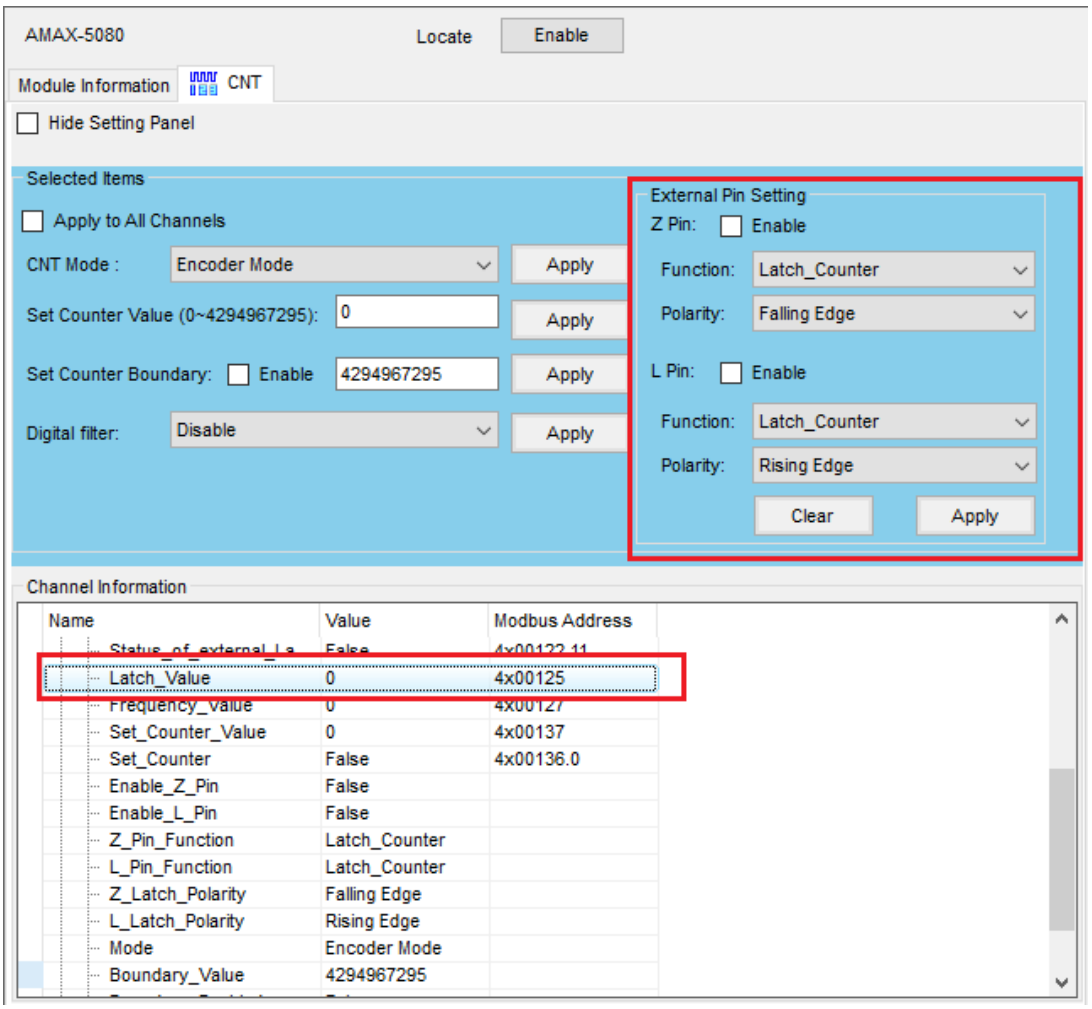

Figure 4.30 Enable the Latch Counter

Chapter 5

Utility Management Tool

5.1 Favorite Group Function

Favorite Group provides saving modules topology for the Utility in order to reduce the rescan time. Utility will load the Favorite Group's data (modules topology) when you restart the Utility. Right-click on the Favorite Group function node, and then click Add New Group in the menu (Figure 5.1).

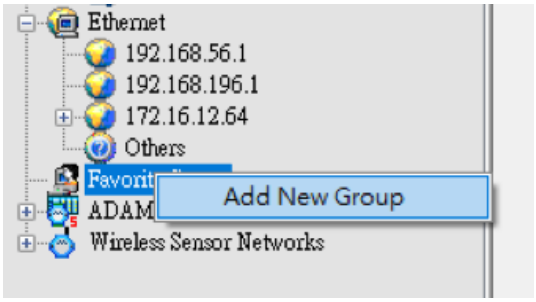

Figure 5.1 Add New Favorite Group

On the Group page, give the group a name and click Add (Figure 5.2).

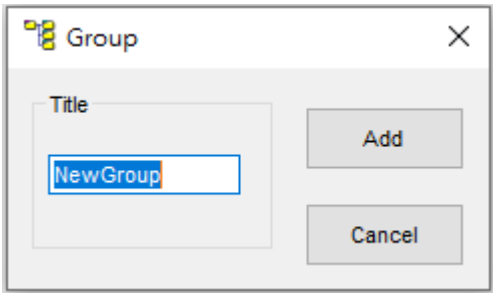

Figure 5.2 Create New Group

Right-click on the New Group (This name can be modified by user), and then click Add New Device in the menu (Figure 5.3).

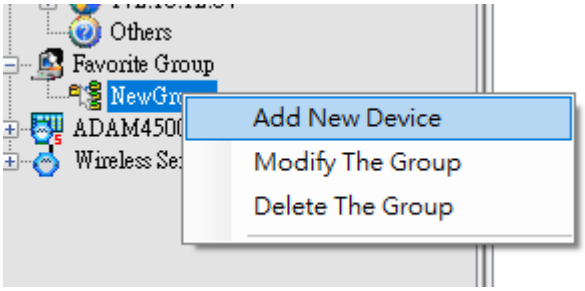

Figure 5.3 Add New Device for Favorite Group

Select the Ethernet Device tab, change the Module typle to AMAX-5070 and key in the IP Address. Click Add for saving change (Figure 5.4).

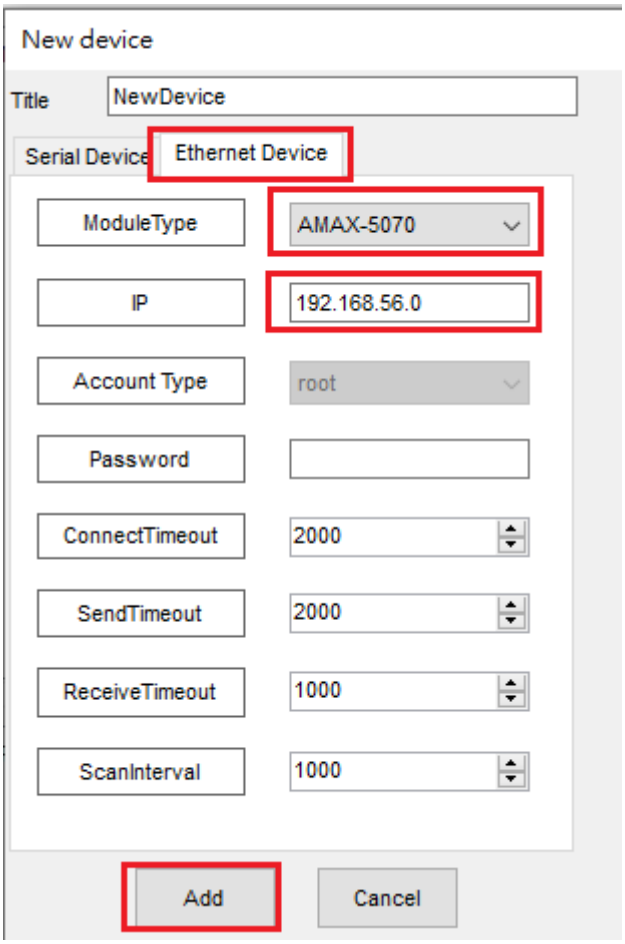

Figure 5.4 Configure the Ethernet Device

The Ethernet device will appear below the NewGroup node after adding new ethernet device. User can click the Diagnosis Connection to detect whether the device is online or not (Figure 69). If all device can be detected online the Connect status will display GOOD (Figure 70), if not it will display CorrespondingFail (Figure 71).

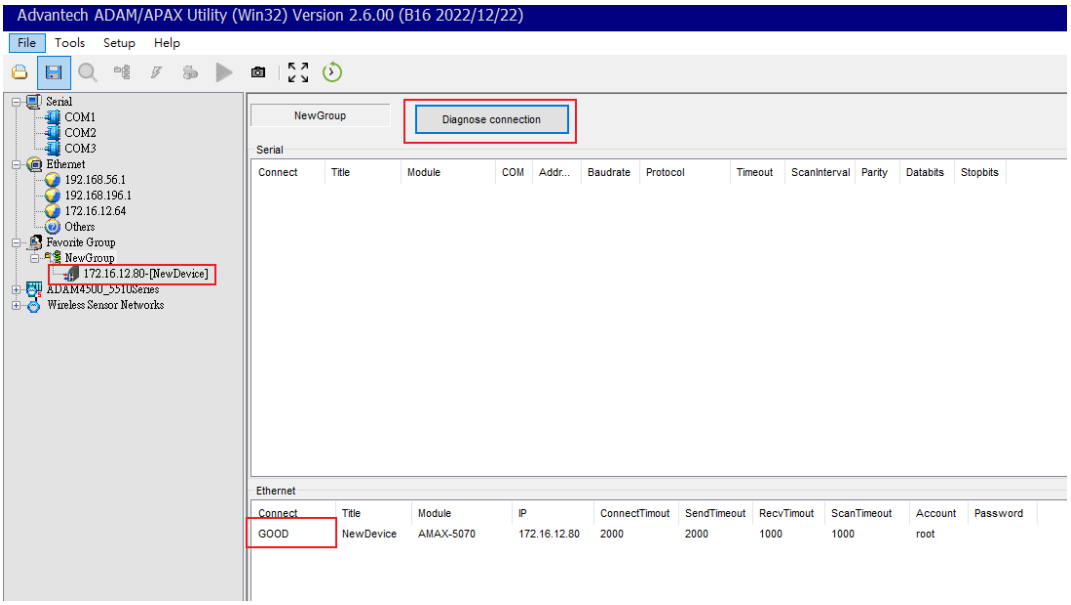

Figure 5.5 New Device Has Been Added Under Newgroup

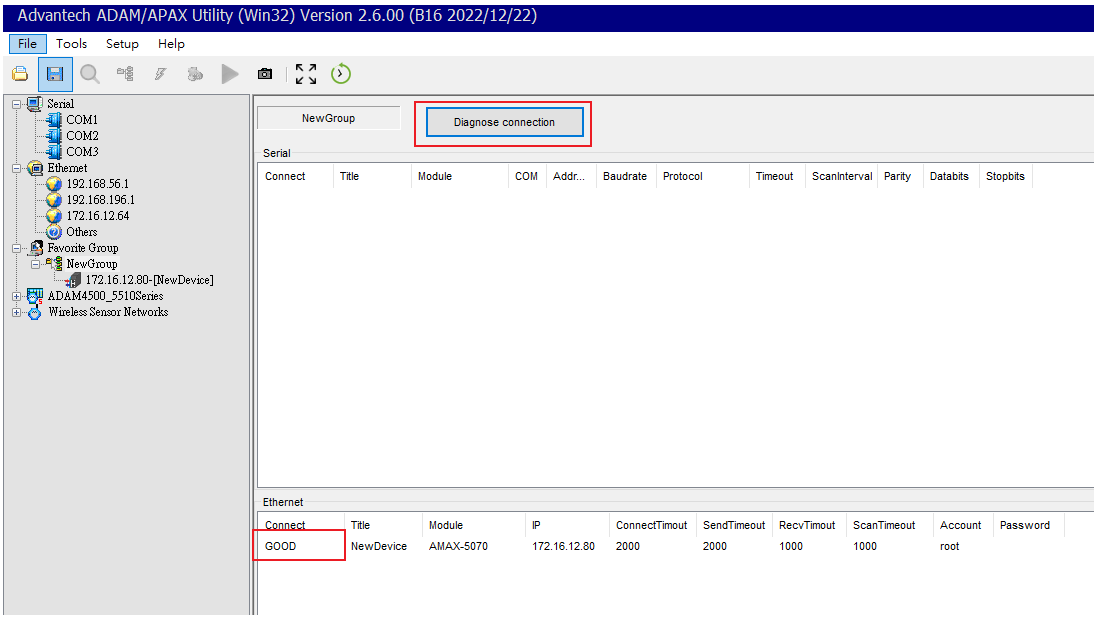

Figure 5.6 Connect Status is GOOD

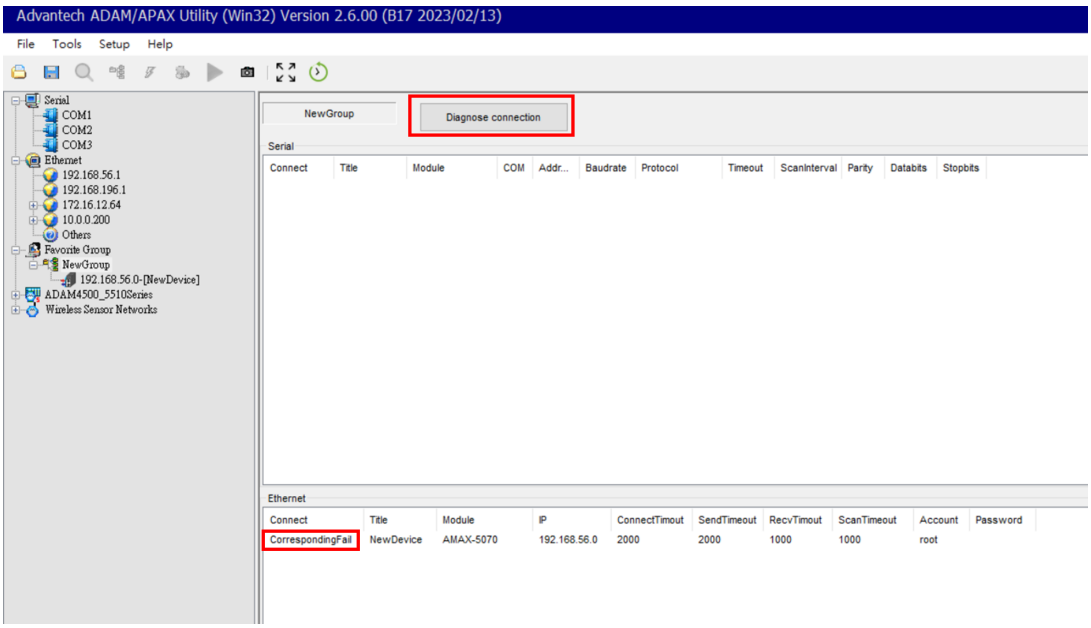

Figure 5.7 Connect Status is CorrespondingFail

User can configure the modules in Favorite Group (Figure 5.8).

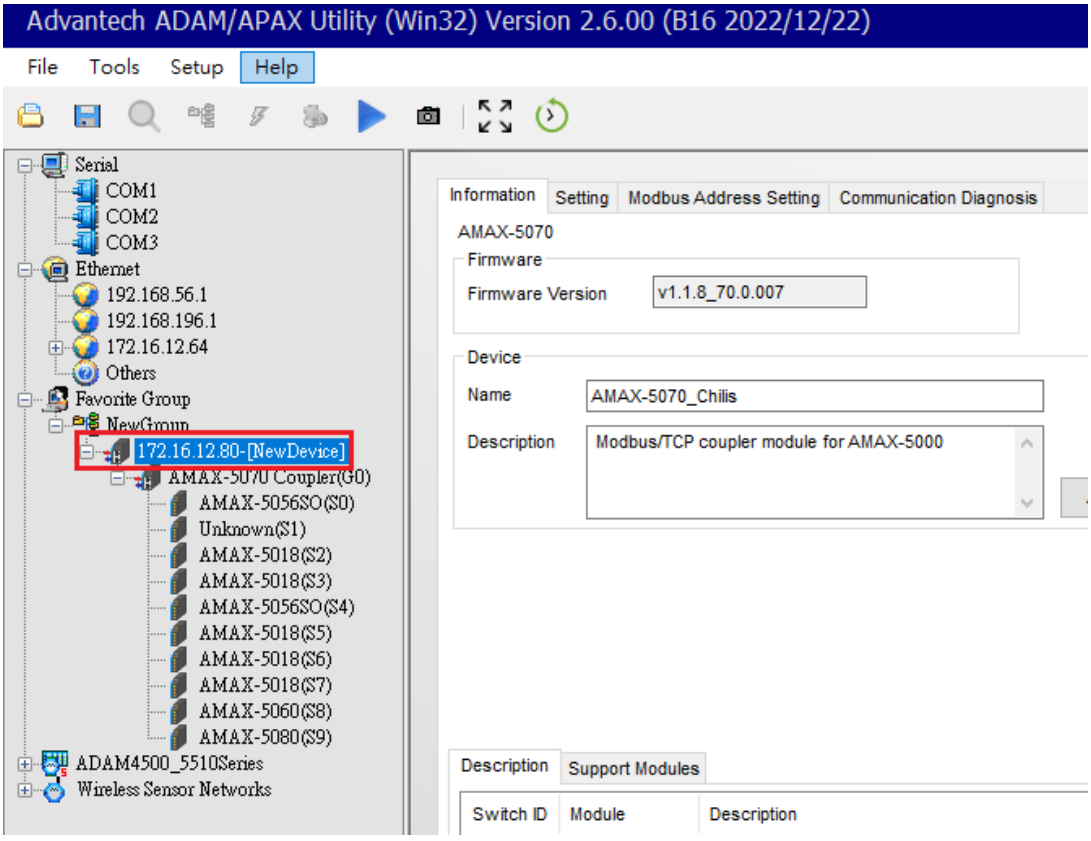

Figure 5.8 Configure the Modules in Favorite Group

5.2 Terminal for Command Testing Function

A terminal for Command Testing Function is supported for users to communicate with SubDevices via Modbus or ASCII command. After searching the Ethernet node, click on the Ethernet node and click the lightning icon (Figure 5.9).

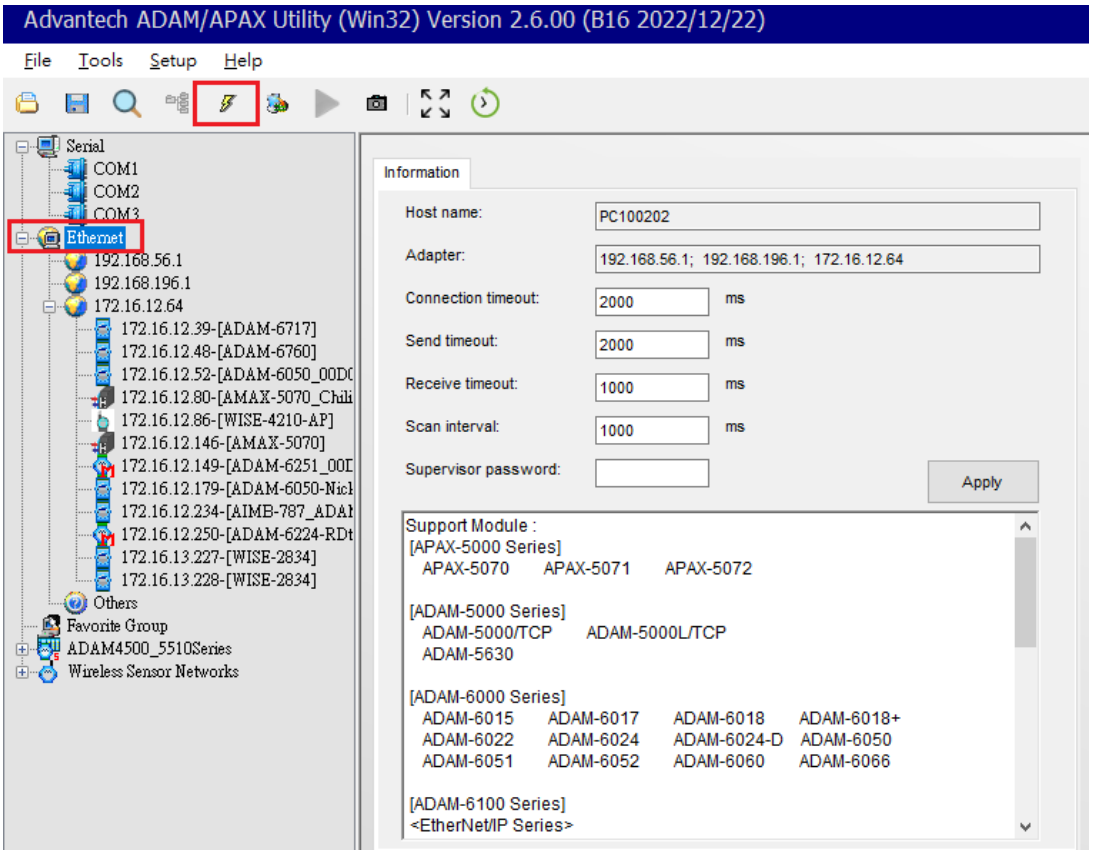

Figure 5.9 Entire the Terminal for Command Testing

Select the AMAX-5070's address and click the Connect button (Figure 5.10).

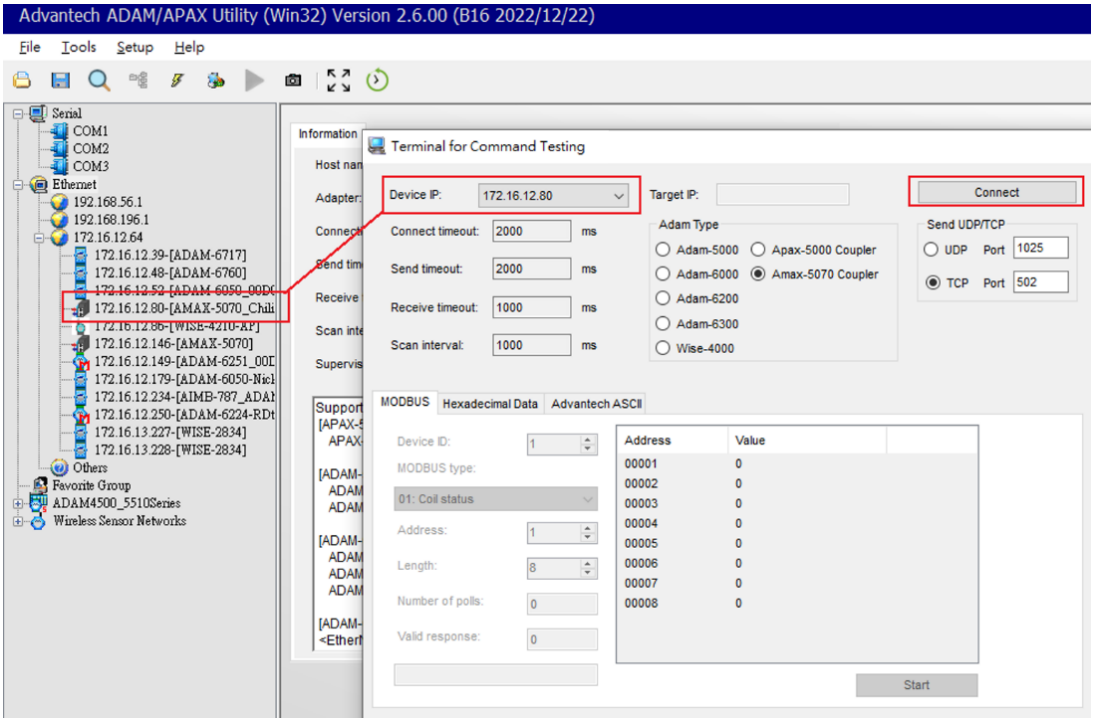

Figure 5.10 Connect to AMAX-5070 via Terminal for Command Testing

Select Modbus Type and click Start button to get Modbus information (Figure 5.11).

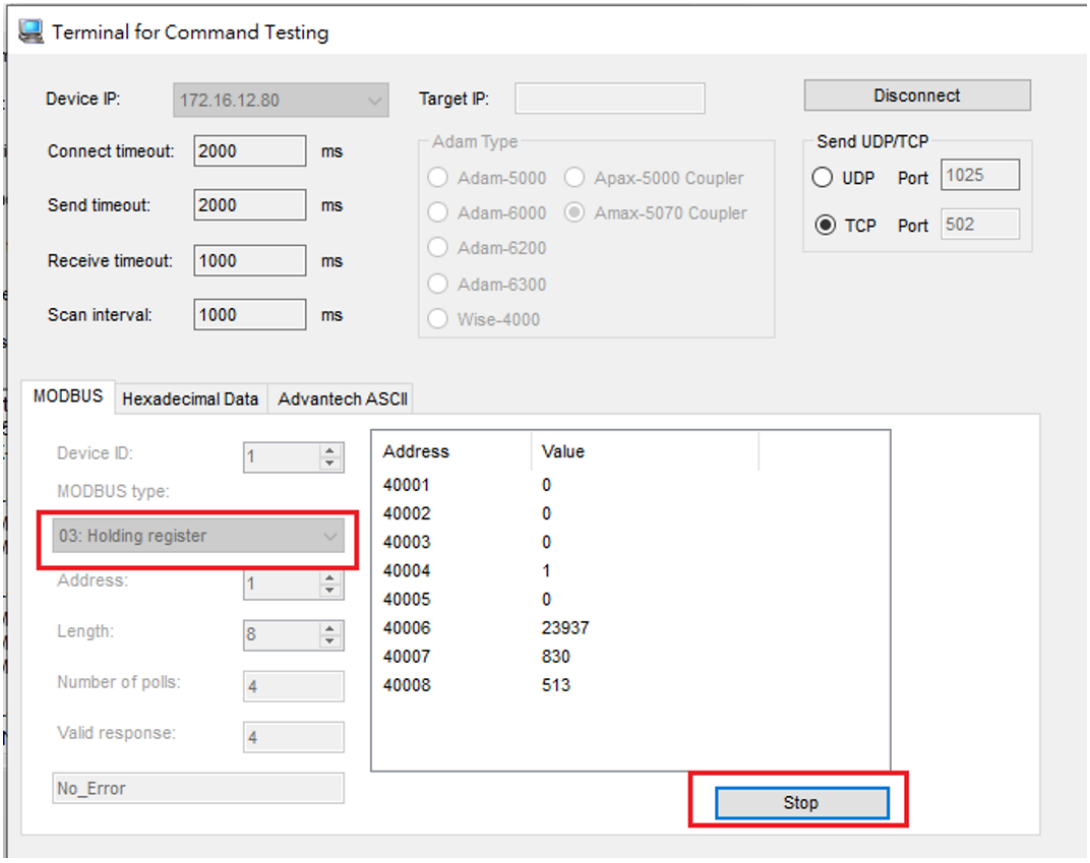

Figure 5.11 Modbus Information in Terminal for Command Testing

Click Disconnect and change from TCP to UDP in Send UDP/TCP. Click the Advantech ASCII tab and test the ASCII command (Figure 5.12).

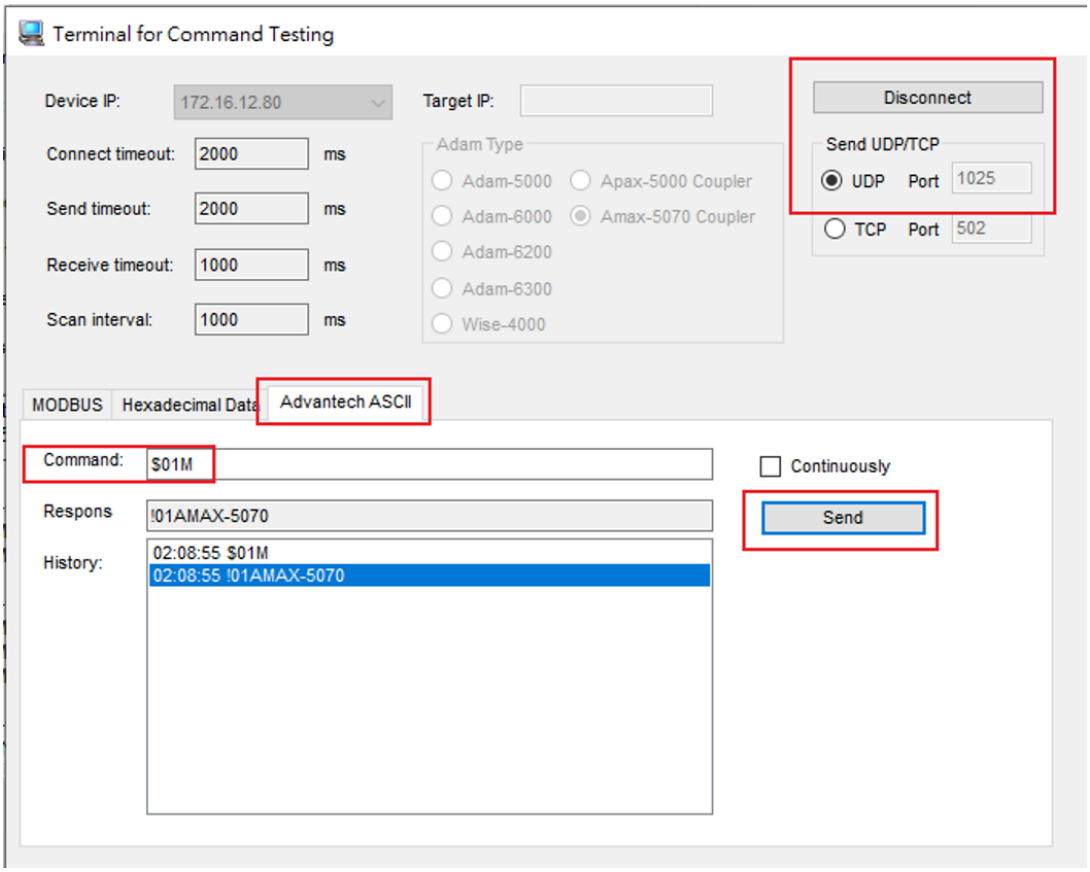

Figure 5.12 ASCII command in Terminal for Command Testing

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Please verify specifications before quoting. This guide is intended for reference purposes only.

All product specifications are subject to change without notice.